

On Matrices Leaving Invariant a Nontrivial Convex Set

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ABSTRACT

A real square matrix A leaves a nontrivial convex set invariant if there exists a convex set C , which is not a linear subspace, such that $A(C) \subset C$. It is shown that this is equivalent to the statement that A has an eigenvalue λ with $\lambda \geq 0$ or $|\lambda| \leq 1$.

INTRODUCTION

There are some results in matrix theory relating geometrical and spectral properties of a matrix. We mention only the following:

THEOREM α . *A real square matrix leaves a bounded symmetric convex set with nonvoid interior invariant if and only if all eigenvalues have moduli less or equal to 1 and the eigenvalues with modulus 1 have index 1.*

THEOREM β . *A real square matrix leaves a solid pointed closed (convex) cone invariant if and only if the spectral radius is an eigenvalue and has maximal index among all eigenvalues with the same modulus.*

Theorem α is only a reformulation of the result in [3, p. 47] using the well-known relation between vector norms and convex bodies in R^n , while Theorem β can be found in [5], [1, Theorems (3.2), (3.5)], and for the case of compact operators also in [2, Theorem 3.1]. Several other results of similar type are mentioned or proved in [2], [5], [7].

What can be said in general about the spectrum of a matrix A if A leaves some convex set invariant? To exclude trivialities we restrict ourselves to *nontrivial* convex sets. Here we call a convex set *nontrivial* if it is nonvoid and not a linear subspace. The purpose of this note is to prove that A leaves a nontrivial convex set invariant if and only if A has an eigenvalue λ such that either $\lambda \geq 0$ or $|\lambda| \leq 1$ (Theorem 1).

This will be shown using two results which characterize the existence of a nonnegative real eigenvalue, and of an eigenvalue with modulus less than or equal to 1, of a matrix A by the existence of certain sets invariant under A (Theorems 2 and 3).

Before stating the results explicitly, we collect the necessary notations and concepts, which can be found mostly in [4, §8, pp. 60–65], or in [6].

We call a nonvoid set $K \subset R^n$ a *cone* if for $\alpha, \beta \geq 0$, $\alpha K + \beta K \subset K$. The linear subspace $L = K \cap (-K)$ is called its *lineality space*. According to the definition given above, the cone K is nontrivial if and only if $K \neq L$. The *recession cone* K_1 of a convex set C is the set of all y such that $x + \lambda y \in C$ for all $x \in C$ and all $\lambda \geq 0$. K_1 is a convex cone which is closed for C closed. If C is closed and $A(C) \subset C$, then also $A(K_1) \subset K_1$. This can be seen easily by using Theorem 8.3 in [4, p. 63].

A set of the form $\{z: y^T z \geq 0\}$, where $y \neq 0$, is called a *half space*. We finally remark that if C is a nontrivial convex set, then its closure is also nontrivial. This can be shown by using a separation theorem for convex sets (e.g., Theorem 11.3, p. 97 in [4]).

RESULTS

We now state the results.

THEOREM 1. *For a real square matrix A the following are equivalent:*

- (a) *There exists a nontrivial convex set C such that $A(C) \subset C$.*
- (b) *A has an eigenvalue λ such that $\lambda \geq 0$ or $|\lambda| \leq 1$.*

THEOREM 2. *For a real square matrix A the following are equivalent:*

- (a) *A leaves a half space invariant.*
- (b) *A leaves a nontrivial cone invariant.*
- (c) *A has a nonnegative real eigenvalue.*

THEOREM 3. *For a real square matrix A the following are equivalent:*

- (a) *A leaves a nonvoid bounded set S , $S \neq \{0\}$, invariant.*

- (b) *A leaves a nontrivial bounded convex set C invariant.*
- (c) *A leaves a closed nontrivial convex set with trivial recession cone invariant.*
- (d) *A has an eigenvalue λ such that $|\lambda| \leq 1$.*

PROOFS

We start with the proofs of Theorems 2 and 3.

Proof of Theorem 2. We shall show (a) \Rightarrow (b) \Rightarrow (c) \Rightarrow (a).

(a) \Rightarrow (b): Trivial, since a half space is a nontrivial cone.

(b) \Rightarrow (c): Let K be a nontrivial cone and $A(K) \subset K$. By restricting A to the invariant subspace $L_1 = K - K$, if necessary, we may assume that K has interior points. Hence the dual cone $K^* = \{l \in L_1^*, l(x) \geq 0 \text{ for all } x \in K\}$ is a closed, pointed, nonvoid cone (see e.g., [1, (2.8)]). A^T , the transpose of A considered as mapping $L_1 \rightarrow L_1$, leaves K^* invariant. Again, we may assume that K^* has interior points, and by Theorem β above, A^T has a nonnegative eigenvalue μ . This shows that (c) holds.

(c) \Rightarrow (a) : If $\mu \geq 0$ is an eigenvalue of A , then there exists a left-hand eigenvector $y^T \neq 0$: $y^T A = \mu y^T$. As $y^T x \geq 0$ implies $y^T A x = \mu y^T x \geq 0$, A leaves the half space $\{z: y^T z \geq 0\}$ invariant. ■

Proof of Theorem 3. We shall show (a) \Leftrightarrow (b) \Rightarrow (c) \Rightarrow (d) \Rightarrow (b).

(a) \Rightarrow (b): Denote by C the convex hull of S . Then C is a nontrivial bounded convex set, and from $A(S) \subset S$ we have $A(C) \subset C$. (b) \Rightarrow (a) is trivial.

(b) \Rightarrow (c): We may assume that C is closed. As C is bounded, its recession cone K is $\{0\}$ (see [4, Theorem 8.4, p. 64]), hence trivial. This proves (c).

(c) \Rightarrow (d): Let C be closed and convex, $A(C) \subset C$, and its recession cone K trivial. If $K = \{0\}$, then C is bounded and so is the convex hull H of $C \cup (-C)$. As $A(H) \subset H$, Theorem α gives the existence of an eigenvalue λ with $|\lambda| \leq 1$. So suppose $K \neq \{0\}$. As $K \neq R^n$ (otherwise $C = R^n$), the decomposition $R^n = K \oplus K^\perp$ is nontrivial. Let $C_1 = K^\perp \cap C$. Then $C_1 \neq \{0\}$ and C_1 is bounded. Let P denote the orthogonal projection of R^n onto K^\perp . Then from the well-known relation (see [4, p. 65]) $C = L \oplus (L^\perp \cap C)$, where L is the lineality space of K , and from the fact that $L = K$, we have $C = K \oplus C_1$; hence $P(C) = C_1$ and $PA(C_1) \subset PA(C) \subset P(C) = C_1$.

PA maps the bounded (closed) convex set C_1 into itself, and hence [see the first part of (c) \Rightarrow (d)] PA restricted to K^\perp has an eigenvalue λ , with $|\lambda| \leq 1$. If we choose a basis b_1, \dots, b_n of R^n , where $b_1, \dots, b_r \in K$ and $b_{r+1}, \dots, b_n \in K^\perp$,

then in the block decomposition

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{matrix} \} r \\ \} n-r \end{matrix}$$

$A_{21} = 0$ because $A(K) \subset K$ and $A_{22} = PA/K^\perp$. This shows that the eigenvalues of PA/K^\perp are also eigenvalues of A .

(d) \Rightarrow (b): Let $x \neq 0$ be an eigenvector corresponding to λ , $Ax = \lambda x$. If λ is real, then x can be chosen real and A leaves the bounded convex set $C = \{\alpha x : -1 \leq \alpha \leq 1\}$ invariant. If λ is complex, $\lambda \neq \bar{\lambda}$, then $x = y + iz$ with y, z real and linearly independent. A leaves the subspace L spanned by y, z invariant and has there two different eigenvalues $\lambda, \bar{\lambda}$, $|\lambda| = |\bar{\lambda}| \leq 1$. Hence by Theorem α , applied to the restriction of A to L , we see that A leaves a convex bounded set invariant. ■

REMARK. If (d) holds, it is also possible, by using the "real" Jordan canonical form, to construct a convex set C with trivial recession cone and interior points, such that $A(C) \subset C$.

Proof of Theorem 1. (a) \Rightarrow (b): We may assume that C is closed. Then A leaves the recession cone K_1 of C invariant. If K_1 is nontrivial, then we see from Theorem 2 that A has a nonnegative real eigenvalue. If K_1 is trivial, then we see from Theorem 3 that A has an eigenvalue λ , with $|\lambda| \leq 1$.

(b) \Rightarrow (a): This is an immediate consequence of Theorems 2 and 3. ■

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