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THEOREMS ON CLOSED COVERINGS
OF A SIMPLEX AND THEIR APPLICATIONS
TO COOPERATIVE GAME THEORY

by Tatsuro Ichiishi and Adam Idzik September 1988



Institut für Mathematische Wirtschaftsforschung an der Universität Bielefeld

> Adresse/Address: Universitätsstraße

4800 Bielefeld 1

Bundesrepublik Deutschland Federal Republic of Germany

1. INTRODUCTION

Let N be a nonempty finite set, and let $\{e^j\}_{j \in N}$ be the unit vectors of the (#N)-dimensional Euclidean space \mathbb{R}^N ; $e^j_j = 1$ and $e^j_i = 0$ for every $i \neq j$. Denote by \mathcal{N} the family of nonempty subsets of N (i.e., $\mathcal{N} := 2^N \setminus \{\phi\}$). Given a subset X of \mathbb{R}^N , denote the convex hull of X by co X, the interior of X by \mathring{X} , the relative interior of X by ri X, and the affine hull of X by aff X. The faces of the unit simplex are then given by $\Delta^S := \operatorname{co} \{e^i \mid i \in S\}$ for every $S \in \mathcal{N}$. The simplex Δ^N is endowed with the relativized Euclidean topology. For each $S \in \mathcal{N}$, its characteristic vector is given by $X_S := \mathbb{E}_{i \in S} e^i$. Given two vectors x and y in \mathbb{R}^N , x·y denotes the Euclidean inner product, and the closed line segment joining the two (i.e., co $\{x,y\}$) is denoted by [x,y]. It was sixty years ago when Sperner [25] published the following:

Theorem 1.1 (Sperner [25]). Let $\{C^i\}_{i \in \mathbb{N}}$ be a closed covering of Δ^N such that $\Delta^{N \setminus \{i\}} \cap C^i = \phi$ for every $i \in \mathbb{N}$. Then $C^i \neq \phi$.

A year later, Knaster, Kuratowski and Mazurkiewicz [17] published the following generalization of Theorem 1.1:

Theorem 1.2 (Knaster, Kuratowski and Mazurkiewicz [17]). Let $\{C^i\}_{i \in N}$ be a family of closed subsets of Δ^N such that $\Delta^S \subset \bigcup_{i \in S} C^i$ for every $S \in \mathcal{N}$. Then $\bigcap_{i \in N} C^i \neq \emptyset$.

Actually, each of Theorems 1.1 and 1.2 is easily shown to be equivalent to Brouwer's fixed-point theorem, by using Browder's [3] technique which involves a partition of unity (see the independent work of Border [3] and Dugundji and Granas [5] for the equivalence of Theorem 1.2 and the Brouwer theorem). Fan [6] pointed out that Theorem 1.1 can be re-formulated as:

Theorem 1.3 (Sperner [25]). Let $\{C^i\}_{i \in \mathbb{N}}$ be a closed covering of Δ^N such that $\Delta^{N \setminus \{i\}} \subset C^i$ for every $i \in \mathbb{N}$. Then $\bigcap_{i \in \mathbb{N}} C^i \neq \emptyset$.

(To show the equivalence of Theorems 1.1 and 1.3, use the Lebesgue number.) Let K be a finite set such that $K \supset N$, and let $A := ((a_{ij}))_{i \in N, j \in K}$ and $c := (c_i)_{i \in N}$ be a $(\#N) \times (\#K)$ real matrix and a $(\#N) \times 1$ real matrix respectively such that

$$a_{ij} = \begin{cases} 1 & \text{if } i = j \in \mathbb{N}; \\ 0 & \text{if } i, j \in \mathbb{N} \text{ but } i \neq j; \end{cases}$$

$$c_{i} \geq 0 & \text{for every } i \in \mathbb{N};$$

$$c_{i} > 0 & \text{for some } i \in \mathbb{N}.$$

Notice that $\{x \in \mathbb{R}_+^K \mid A \times = c\} \neq \emptyset$. Theorem 1.3 is a special case of the following Scarf's theorem [20]:

Scarf [19, 20] used the "path-following technique" of Lemke and Howson [18] to establish a theorem on primitive sets (Theorem 4.6 of this paper), and then used the latter theorem to prove Theorem 1.4. An alternative proof of Theorem 1.4 was made by Kannai [15]; he used the Brouwer fixed-point theorem only.

A generalization of Theorem 1.2 was made by Shapley [21]. To formulate Shapley's result we need the following:

Definition 1.5. A subfamily \mathcal{S} of \mathcal{N} is called <u>balanced</u>, if there exists $\{\lambda_S^{}\}_{S \in \mathcal{S}} \subset \mathbb{R}_+$ such that $\Sigma_{S \in \mathcal{S}}: S^3 i \lambda_S = 1$ for every $i \in \mathbb{N}$.

Theorem 1.6 (Shapley [21]). Let $\{C^S\}_{S \in \mathcal{N}}$ be a family of closed subsets of Δ^N such that $\Delta^T \subset \bigcup_{S \subset T} C^S$ for every $T \in \mathcal{N}$. Then there exists a balanced family \mathscr{B} such that $\bigcap_{S \in \mathscr{B}} C^S \neq \emptyset$.

To see the relationship between the conclusions of Theorem 1.4 and of Theorem 1.6, let \tilde{A} be the (#N) × (# \mathcal{N}) matrix whose rows (columns, resp.) are indexed by i ϵ N (by S ϵ \mathcal{N} , resp.) such that column S is precisely X_S . The set $\{x \ \epsilon \ R_+^{\mathcal{N}} \mid \tilde{A} \ x = X_N\}$ is nonempty and bounded. Then the conclusion of Theorem 1.6 is re-formulated as: There exists $x \ \epsilon \ R_+^{\mathcal{N}}$ such that

$$\tilde{A} \times = X_N$$
, and
$$\cap \{C^S \mid S \in \mathcal{N}, x_S > 0\} \neq \phi.$$

Actually, motivatied by Billera's generalization [1, 2] of Scarf's theorem [19] for nonemptiness of the core (Theorem 4.4 in this paper), Shapley [21] established a more general theorem (Theorem 1.6' below). Define $\Pi := \times \sup_{S \in \mathcal{N}} \Delta^S$.

Definition 1.5'. Choose any $\pi:=(\pi_S)_{S\in\mathcal{N}}\in\Pi$. A subfamily \mathcal{S} of \mathcal{N} is called π -balanced, if π_N ε co $\{\pi_S\mid S\in\mathcal{S}\}$.

Theorem 1.6' (Shapley [21]). Let $\{C^S\}_{S \in \mathcal{N}}$ be a family of closed subsets of Δ^N such that $\Delta^T \subset U$ C^S for every $T \in \mathcal{N}$. Choose any $\pi \in S \subset T$.

Then there exists a π -balanced family \mathcal{S} such that $C^S \neq \emptyset$.

The additional assumption in Shapley [21] that $\pi \in \operatorname{ri} \Pi$ is non-essential: For an arbitrary $\pi \in \Pi$, choose a sequence in $\operatorname{ri} \Pi$ which converges to π . Theorem 1.6 is a special case of Theorem 1.6' in which $\pi_S = \chi_S/(\$S)$. Shapley [21] proved Theorem 1.6' by using the "path-following technique" of Lemke and Howson [18]. Todd [26, 27] has a proof of Theorem 1.6 which makes use of the Brouwer fixed-point theorem and a sequence of simplicial partitions. Shapley [22] has a shorter proof of Theorem 1.6 using Kakutani's fixed-point theorem. Ichiishi [12] has a yet shorter proof of Theorem 1.6 using Fan's [7] coincidence theorem; see also Ichiishi [13].

Recently Ichiishi [14] established the following theorem, which is dual to Theorem 1.6 just as Theorem 1.3 is dual to Theorem 1.2, and which is also a generalization of Theorem 1.3:

Theorem 1.7 (Ichiishi [14]). Let $\{c^S\}_{S \in \mathcal{N}}$ be a family of closed subsets of Δ^N such that $\Delta^T \subset \bigcup_{S \supset N \setminus T} c^S$ for every $T \in \mathcal{N}$. Then there exists a balanced family \mathcal{J} such that $\bigcap_{S \in \mathcal{J}} c^S \neq \emptyset$.

It was pointed out by David Schmeidler that Theorems 1.6 and 1.7 are equivalent; Schmeidler's argument is reproduced in Ichiishi [14]. Neither of Theorems 1.4 and 1.7 includes the other.

The first purpose of the present paper is to establish general theorems on closed coverings of a simplex in order to give a unified treatment of the above theorems. We prove these general theorems by using a certain geometric lemma and the following special case of Fan's [7, 9] coincidence theorem:

Theorem 1.8 (Fan [9]). Let X be a nonempty, compact and convex subset of \mathbb{R}^N , and let F and G be upper semicontinuous correspondences from X to the subsets of \mathbb{R}^N , such that both F(x) and G(x) are nonempty, compact, and convex for each $x \in X$, and such that

 $(\forall x \in X)$: $(\forall p \in R^N : p \cdot x = \min p \cdot X)$:

 $u \in F(x)$: $u \in G(x)$: $v \cdot u \leq v \cdot v$.

Then there exists $x^* \in X$ such that $F(x^*) \cap G(x^*) \neq \phi$.

Other covering properties of convex sets were given, e.g., by Fan [6, 8, 10, 11] and Shih and Tan [23, 24].

The second purpose of the present paper is to clarify relationships between the above theorems on closed coverings of a simplex and certain theorems related to the core of a cooperative game without side-payments.

2. MAIN RESULTS

Let K, A, c be given as in the paragraph that precedes the statement of Theorem 1.4. Denote column j of the matrix A by a^{j} .

Theorem 2.1. Assume that $c \in \Delta^N$ and $a^j \in aff \Delta^N$ for every $j \in K$.

Let $\{c^j\}_{j \in K}$ be a closed covering of Δ^N such that

 $\forall \ T \in \mathcal{N} \setminus \{N\}: \ \Delta^T \subset \cup \{C^j \mid j \in K, \ a^j \in \Delta^T\}.$ $\underline{\text{Then there exists a subset}} \ I \ \underline{\text{of}} \ K \ \underline{\text{such that}} \ c \in co \{a^j \mid j \in I\} \ \underline{\text{and}}$ $\bigcap \ C^j \neq \phi.$ $j \in I$

Proof of Theorem 2.1. For each $x \in \Delta^N$ define $I(x) := \{j \in K \mid C^j \ni x\}$, $F(x) := \{c\}$, and $G(x) := co \{a^j \mid j \in I(x)\}$. Then the correspondeces F and G from Δ^N to the subsets of aff Δ^N are upper semicontinuous with nonempty compact and convex values. Choose $x \in \Delta^N$ and $p \in R^N$ such that $p \cdot x = \min p \cdot \Delta^N$. There exists a unique $S \subset N$ such that $x \in ri \Delta^S$. Thus we have $p \cdot y = \min p \cdot \Delta^N$ for all $y \in \Delta^S$. If S = N, then for all $u \in F(x)$ and all $v \in G(x)$, $p \cdot u = p \cdot v$. If $S \neq N$, then by the assumption of the present theorem there exists $j \in K$ such that $a^j \in \Delta^S$ and $x \in C^j$. For this j, $a^j \in G(x)$ and $p \cdot a^j = \min p \cdot \Delta^N \leq p \cdot c$. All the assumptions of Theorem 1.8 are now satisfied, so there exists $x \notin \Delta^N$ such that $F(x \not \sim R)$ of $G(x \not\sim R)$ and $F(x \not\sim R)$ is the required set $F(x \not\sim R)$.

A generalization of Theorem 2.1 is given by:

Theorem 2.2. Assume that $c \in \Delta^N$ and that the set $\{x \in R_+^K \mid A \mid x = c\}$ is bounded. Let $\{C^j\}_{j \in K}$ be a closed covering of Δ^N such that $\forall T \in \mathcal{N} \setminus \{N\} \colon \Delta^T \subset U \ \{C^j \mid j \in K, \ a^j \in \Delta^T\}.$

Then there exists $x \in \mathbb{R}_{+}^{K}$ such that $A \times = c$ and $A \times C^{j} \mid X_{j} > 0 \neq 0$.

We shall provide two proofs of this theorem. Both proofs make use of the following claim:

Claim 2.3. Let $n \le k$, let A be an $n \times k$ matrix whose first n columns constitute the unit matrix, and let c be an $n \times 1$ nonnegative matrix. Then the following two conditions (i) and (ii) are equivalent.

- (i) Set $\{x \in \mathbb{R}^k_+ \mid A \mid x = c\}$ is bounded; and
- (ii) $\neg \exists x \in \mathbb{R}^k \setminus \{0\} : A \times = 0.$

Moreover, for any $n \times 1$ nonnegative, nonzero matrix d, any of the conditions (i) and (ii) implies the following condition (iii).

(iii) $\neg \exists x \in \mathbb{R}^k_+$: A x = -d.

Proof of Theorem 2.2, Using Theorem 2.1. Define $D := \{A \times | \times \epsilon R_+^K. \}$ $\Sigma_{j \in K} \times_j = 1\}$; it is a convex compact subset of R^N . By Claim 1.3 (ii) and (iii), $D \cap (-R_+^N) = \phi$. There exists, therefore, a hyperplane H which

stricly separates D and $-R_+^N$, in particular $0 \notin H$. Then for each $y \in D$ there exists a unique vector $\hat{y} \in [0, y] \cap H$. Notice that $c \in D$, and $a^j \in D$, for every j (in particular, $\Delta^N \subset D$). Define $\hat{\Delta}^S := \{\hat{y} \mid y \in \Delta^S\}$, and $\hat{C}^j := \{\hat{y} \mid y \in C^j\}$. Under the assumption of Theorem 2.2,

 $\forall \ T \in \mathcal{N} \setminus \{ \mathbf{N} \} \colon \ \hat{\Delta}^{\overline{\mathbf{T}}} \subset \cup \ \{ \hat{\mathbf{C}}^{\mathbf{j}} \ | \ \mathbf{j} \ \in K. \ \hat{\mathbf{a}}^{\mathbf{j}} \ \in \hat{\Delta}^{\overline{\mathbf{T}}} \} \,.$

By Theorem 2.1 applied to $(\hat{\Delta}^N, \{\hat{a}^j\}_{j \in K}, \hat{c}, \{\hat{C}^j\}_{j \in K})$, there exists $I \in K$ such that $\hat{c} \in co \{\hat{a}^j \mid j \in I\}$ and $\bigcap \{\hat{C}^j \mid j \in I\} \neq \emptyset$. We can now choose a suitable $x \in \mathbb{R}_+^K$ such that $x_j = 0$ for $j \in K \setminus I$, $A \times = c$ and $\bigcap \{\hat{C}^j \mid x_j > 0\} \neq \emptyset$.

Proof of Theorem 2.2, Using Theorem 1.8. Define

$$\forall j \in K : \hat{a^j} := a^j + (1 - \Sigma_{i \in N} a_{ij}) c.$$

Then, \hat{a}^j saff Δ^N for every j s K, and $\hat{a}^j = a^j$ if a^j saff Δ^N . Define for each $x \in \Delta^N$,

$$F(x) := \{c\},\$$

$$G(x) := co \{\hat{a}^{j} \mid j \in K. \quad C^{j} \ni x\}.$$

As in the proof of Theorem 2.1, one can show that all the assumptions of Theorem 1.8 are satisfied, so there exists $x* \in \Delta^N$ such that $F(x*) \cap G(x*) \neq \phi$. Define $I := \{j \in K \mid C^j \ni x*\}$. Then there exists $\{z_j\}_{j \in I} \subset R_+$ such that $c = \sum_{j \in I} z_j \hat{a}^j$. By substituting the definition of \hat{a}^j 's and by setting $t_j := 1 - \sum_{i \in N} a_{ij}$, one obtains

$$c = \sum_{j \in I} z_j (a^j + t_j c).$$

To sum up, there exist $z_i \in \mathbf{R}_+$, $i \in I$, not all zero, such that

$$(1 - \sum_{j \in I} z_j t_j) c = \sum_{j \in I} z_j a^j.$$

By Claim 2.3,

$$1 - \sum_{j \in I} z_j t_j > 0,$$

thus there exists $\mathbf{z}^{\star} \in \mathbf{R}_{+}^{K}$ such that

A
$$z* = c$$
, and

$$\cap \{C^{j} \mid z_{j}^{*} > 0\} \supset \cap C^{j} \neq \emptyset.$$
 Q.E.D.

Now we generalize Theorem 1.7. We need the following geometric lemma:

Lemma 2.4. Let C be a compact, convex subset of \mathbb{R}^N , and let F be a finite subset of ∂C , the relative boundary of C. Choose any c ε ri co F. For each $x \varepsilon F$ choose $x' \varepsilon \partial C$ so that $c \varepsilon [x, x']$, and define $F' := \{x' \mid x \varepsilon F\}$. Then $c \varepsilon co F'$.

Proof of Lemma 2.4. There exists $\{\alpha_{\mathbf{X}}\}_{\mathbf{X} \in \mathbf{F}} \subset \mathbf{R}_{+}$, $\Sigma_{\mathbf{X} \in \mathbf{F}} \alpha_{\mathbf{X}} = 1$, such that $\mathbf{C} = \Sigma_{\mathbf{X} \in \mathbf{F}} \alpha_{\mathbf{X}} \times \mathbf{F}$ for each $\mathbf{X} \in \mathbf{F}$ there exists $\beta_{\mathbf{X}}$, $0 < \beta_{\mathbf{X}} < 1$, such that $\mathbf{C} = \beta_{\mathbf{X}} \times \mathbf{F} + (1 - \beta_{\mathbf{X}}) \times \mathbf{Y}$. Then $\mathbf{C} = \Sigma_{\mathbf{X} \in \mathbf{F}} \alpha_{\mathbf{X}} (\mathbf{C} - (1 - \beta_{\mathbf{X}}) \times \mathbf{Y}) / \beta_{\mathbf{X}}$, so $((\Sigma_{\mathbf{X} \in \mathbf{F}} \alpha_{\mathbf{X}} / \beta_{\mathbf{X}}) - 1) \mathbf{C} = \Sigma_{\mathbf{X} \in \mathbf{F}} (\alpha_{\mathbf{X}} / \beta_{\mathbf{X}} - \alpha_{\mathbf{X}}) \times \mathbf{Y}$, therefore $\mathbf{C} \in \mathbf{C} \in \mathbf{F}'$. Q.E.D.

Theorem 2.5. Assume that c ϵ ri Δ^N and a^j ϵ aff Δ^N for every j ϵ K.

Assume also that for every j ϵ K for which a^j ϵ $\partial \Delta^N$, there exists j' ϵ K such that $a^{j'}$ ϵ $\partial \Delta^N$ and c ϵ $[a^j, a^{j'}]$. Let $\{c^j\}_{j \epsilon K}$ be a closed covering of Δ^N such that

 $\forall \ T \in \mathcal{N} \setminus \{N\} \colon \ \Delta^T \subset \cup \ \{C^{j'} \ \big| \ j \in K. \ a^j \in \Delta^T\}.$

Then there exists a subset I of K such that c ϵ co $\{a^j \mid j \in I\}$ and $\cap C^j \neq \phi$.

Proof of Theorem 2.5. Define $D^j:=C^{j'}$ for every j for which a^j ϵ $\partial \Delta^N$, and $D^j:=C^j$ for all other j. All the assumptions of Theorem 2.1 are satisfied for $(\Delta^N, \{a^j\}_{j \in K}, c, \{D^j\}_{j \in K})$, so there exists a subset I of K such that $c \in co \{a^j \mid j \in I\}$ and $\bigcap D^j \neq \emptyset$. Define $I':=\{j' \mid j \in I\}$. By Lemma 2.4, $c \in co \{a^j \mid j \in I'\}$. Moreover, $\bigcap C^j = \bigcap D^j \neq \emptyset$. $j \in I$ $j \in I$.

Using the same method and Theorem 2.2, we can prove:

Theorem 2.6. Assume that c ϵ ri Δ^N and that the set $\{x \in \mathbb{R}_+^K \mid A \times = c\}$ is bounded. Assume also that for every $j \in K$ for which $a^j \in \partial \Delta^N$,

there exists j' ϵ K such that $a^{j'}$ ϵ $\partial \Delta^N$ and c ϵ $[a^j, a^{j'}]$. Let $\{c^j\}_{j \in K}$ be a closed covering of Δ^N such that

 $\forall \ T \ \epsilon \ \mathcal{N} \setminus \{N\} \colon \ \Delta^T \subset \cup \ \{c^{j'} \ \big| \ j \ \epsilon \ K, \ a^j \ \epsilon \ \Delta^T\}.$

Then there exists $x \in \mathbb{R}_{+}^{K}$ such that $A \times = c$ and $A \times C^{j} \mid X_{j} > 0 \neq \phi$.

3. REMARKS

The K-K-M theorem (Theorem 1.2) follows from Theorem 2.1 if we take K=N and $C \in I$ Δ^N . Scarf's theorem (Theorem 1.4) for the case $C \in I$ Δ^N follows from Theorem 2.6 if we introduce new columns $\{a^S \mid S \in \mathcal{N} \setminus \{N\}, \#S \geq 2\}$ (so that if $\#N \geq 2$, the new matrix consists of $(\#K + \#\mathcal{N} - 1 - \#N)$ columns) defined by $a^S \in \Delta^S$ and $C \in [a^S, a^{N \setminus S}]$, and take $C^S = \bigcap_{i \in S} C^i$ for each $S \in \mathcal{N}$ (Theorem 1.4 would be trivial if $C \in \partial \Delta^N$). Shapley's theorem (Theorem 1.6') follows from Theorem 2.2 if we take $K = \mathcal{N}$, a^S (:= column $C \in I$ column $C \in I$ follows from Theorem 2.2 if we take $C \in I$ theorem (Theorem 1.7) follows from Theorem 2.6 if we take $C \in I$ and $C \in I$ theorem 1.7) follows from Theorem 2.6 if we take $C \in I$ and $C \in I$ theorem 1.7) follows from Theorem 2.6 if we take $C \in I$ and $C \in I$ theorem 1.7)

All the results in Section 2 are valid for an arbitrary real matrix A of dimension (#N) \times (#K), $N \subseteq K$, in which there are #N linearly independent columns, and c (\neq 0) is a nonnegative linear combination of those columns.

Theorems similar to those of Section 2 can be proved for a compact polyhedron instead of a simplex.

4. CORE

The finite set N is now interpreted as the set of players, and ${\cal N}$ as the family of nonempty coalitions.

Definition 4.1. A non-side-payment game is a function V from $\mathcal N$ to the subsets of $\mathbb R^N$ such that for every $S \in \mathcal N$, V(S) is a cylinder, i.e., $[u, v \in \mathbb R^N, V i \in S: u_i = v_i]$ implies $[u \in V(S)]$ iff $v \in V(S)$.

The set V(S), or rather its projection to \mathbb{R}^S , is interpreted as the set of utility allocations within S, each is made feasible by some coordination of strategies of the members of S.

Definition 4.2. The <u>core</u> of a non-side-payment game V is the set C(V) of all $u \in \mathbb{R}^N$ such that (a) $u \in V(N)$ and (b) it is not true that there exist $S \in \mathcal{N}$ and $u' \in V(S)$ such that $u_i < u_i'$ for every $i \in S$.

The core is a typical solution concept; condition (a) says that the utility allocation u is feasible within the grand coalition N, and condition (b) says that no coalition can improve upon u.

Definition 4.3 A non-side-payment game V is called <u>balanced</u> if for every balanced subfamily \mathcal{S} of \mathcal{N} , $\cap_{S_{\mathcal{E}},\mathcal{S}}$ V(S) \subset V(N).

See, e.g., Ichiishi [13, Chapter 5] for further discussions of Definitions 4.1, 4.2 and 4.3. Scarf's [19] fundamental theorem for nonemptiness of the core:

Theorem 4.4 (Scarf [19]). Let $V: \mathcal{N} \to 2^{\mathbb{R}^N}$ be a non-side-payment game, and define $b \in \mathbb{R}^N$ by $b_i := \sup \{u_i \in \mathbb{R} \mid u \in V(\{i\})\}$ for each $i \in \mathbb{N}$. The core of V is nonempty if (i) $V(S) - \mathbb{R}^N_+ = V(S)$ for every $S \in \mathcal{N}$; (ii) there exists $M \in \mathbb{R}$ such that for every $S \in \mathcal{N}$, $[u \in V(S) \cap [\{b\} + \mathbb{R}^N_+]]$ implies $[u_i \in M]$ for every $i \in S$; (iii) V(S) is closed in \mathbb{R}^N for every $S \in \mathcal{N}$; and (iv) V is balanced.

Scarf [19] established the following Theorem 4.6, and then derived from it Theorem 4.4. Let K, A, c be given as in the paragraph that precedes the statement of Theorem 1.4. Choose vectors $P := \{\pi^j\}_{j \in K}$ in \mathbb{R}^N such that

$$\pi^{i} = (R_{i}, \dots, R_{i}, 0, R_{i}, \dots, R_{i}) \text{ if } i \in N;$$

$$\pi^{j} \in (\Delta^{N} - R_{+}^{N}) \cap R_{+}^{N} \text{ if } j \in K \setminus N,$$

where $R_i > 1$ for each $i \in N$.

Definition 4.5. A subset of P, $\{\pi^j\}_{j \in I}$, is called a <u>primitive set</u>, if there does not exist $\pi \in P$ such that

Vien: $\pi_i > \min \{\pi_i^j \mid j \in I\}.$

Theorem 4.6 (Scarf [19, 20]). If the set $\{x \in R_+^K \mid A \times = c\}$ is bounded, then there exists $x \in R_+^K$ such that $A \times = c$ and $\{\pi^j \mid j \in K, \times_j > 0\}$ is a primitive set.

Remark that the vectors π^j , j ϵ K\N, can actually be chosen arbitrarily from R_+^N , provided that the R_i , i ϵ N, are suitably re-defined. Due to arbitrariness of the finite set K (provided that it contains N), and hence the generality of matrix A compared with \tilde{A} (the matrix \tilde{A} was introduced in a paragraph between the statement of Theorem 1.6 and Definition 1.5'), Theorem 4.6 together with a certain nondegeneracy assumption summarizes an analytical feature of Scarf's algorithm to compute a member of the core.

It was pointed out earlier that Scarf [20] derived Theorem 1.4 from Theorem 4.6. Conversely, Theorem 4.6 can be derived from Theorem 1.4; the proof is based on the idea in Vohra [28]:

Derivation of Theorem 4.6 from Theorem 1.4. Define $C_1^j := \{\pi^j\} - R_+^N$. Denote by F the boundary of $U_{j \in K} C_1^j$, and define for each $j \in K$, $C^j := \{z \in \Delta^N \mid \exists y \in C_1^j \cap F \colon z = y / \Sigma_{i \in N} y_i\}.$

If $\pi \not \in \overset{\circ}{R}^N_+$ for any $\pi \in P$, then the assertion of Theorem 4.6 is trivial. Assume, therefore, that there exists $\pi \in P \cap \overset{\circ}{R}^N_+$. Then 0 is in the interior of $U_{j \in K} C_1^j$, so $\{C^j\}_{j \in K}$ is a closed covering of Δ^N . Observe that $y \in F$, if $y \in U_{j \in K} C_1^j$ and $y_i \geq R_i$ for some $i \in N$. By this observation, it is easy to check $\Delta^{N \setminus \{j\}} \subset C^j$. Thus $\{C^j\}_{j \in K}$ satisfies the assumption of Theorem 1.4, so there exists $x^* \in R^K_+$ such that $A \times x^* = C$ and $A \cap \{C^j \mid j \in K, x^* \mid j > 0\} \neq \emptyset$. Set $A \cap_{j \in I} C^j$, and consider $A \cap_{j \in I} C^j$ is the required primitive set.

Many alternative proofs of Theorem 4.4 have appeared in the literature: Shapley [21] derived Theorem 4.4 from Theorem 1.6. Keiding and Thorlund-Petersen [16] and Vohra [28] proved Theorem 4.4, using Theorem 1.2 and Kakutani's fixed-point theorem, respectively. Ichiishi [14] pointed out that the geometric insights of Keiding and Thorlund-Petersen and of Vohra can be re-formulated as Theorem 1.7. It will be shown here that Theorem 4.4 follows simply from a theorem which is weaker than Theorem 1.4 and weaker than Theorem 1.7; the proof is based on the idea in Vohra [28]:

Derivation of Theorem 4.4 either from Theorem 1.4 or from Theorem 1.7. The special case of Theorem 1.4 and of Theorem 1.7, in which $K = \mathcal{N}$, $A = \tilde{A}$ and $c = X_N$, will be used here. Assume without loss of generality that

b = 0. If $0 \not\in \mathring{V}(S)$ for every $S \in \mathcal{N}$, then there is nothing to prove (indeed, in this case, $0 \in C(V)$). Assume, therefore, that $0 \in \mathring{V}(S)$ for some $S \in \mathcal{N}$. Choose two real numbers M_1 and M_2 such that $M_1 > M_2 > M_1$, and denote by F the boundary of the set,

$$\begin{array}{c|c} U & \{u \in V(\{i\}) \mid \forall k \in N \setminus \{i\}: u_k \leq M_1\} \\ i \in N \end{array}$$

For each $\pi \in \Delta^N$, consider the unique point $f(\pi) \in F \cap \mathbb{R}^N_+$ defined by $\pi = f(\pi) / \Sigma_{i \in N} f_i(\pi)$. Define $C^S := \{\pi \in \Delta^N \mid f(\pi) \in V(S)\}$ for every $S \in \mathcal{N}$. The family $\{C^S\}_{S \in \mathcal{N}}$ is a closed covering of Δ^N , and it is easy to check $\Delta^{N \setminus \{j\}} \subset C^{\{j\}}$ for every $j \in N$. All the assumptions of Theorem 1.4 and of Theorem 1.7 are satisfied, so there exist $x \in \mathbb{R}^N_+$ and $\pi \star \in \Delta^N$ such that $\tilde{A} \times x^* = X_N$ and $\pi^* \in \Lambda \cap \{C^S \mid S \in \mathcal{N}, \times x_S^* > 0\}$. The point $f(\pi^*)$ will be shown to be a member of C(V). The family $\mathcal{S} := \{S \in \mathcal{N} \mid x_S^* > 0\}$ is balanced and $f(\pi^*) \in \Lambda_S \cap \{C^S \mid S \in \mathcal{N}, \times Y_S > 0\}$. So by the balancedness assumption on V, $f(\pi^*) \in V(N)$. Consequently, $f(\pi^*) \in \{u \in F \mid V \in N: u_i \in M\}$, which implies that the utility allocation $f(\pi^*)$ cannot be improved upon by any coalition.

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