Splitting polytopes

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Abstract. A split of a polytope P is a (regular) subdivision with exactly two maximal cells. It turns out that each weight function on the vertices of P admits a unique decomposition as a linear combination of weight functions corresponding to the splits of P (with a split prime remainder). This generalizes a result of Bandelt and Dress [Adv. Math. 92 (1992)] on the decomposition of finite metric spaces.

Introducing the concept of *compatibility* of splits gives rise to a finite simplicial complex associated with any polytope P, the *split complex* of P. Complete descriptions of the split complexes of all hypersimplices are obtained. Moreover, it is shown that these complexes arise as subcomplexes of the tropical (pre-)Grassmannians of Speyer and Sturmfels [Adv. Geom. 4 (2004)].

1. Introduction

A real-valued weight function w on the vertices of a polytope P in \mathbb{R}^d defines a polytopal subdivision of P by way of lifting to \mathbb{R}^{d+1} and projecting the lower hull back to \mathbb{R}^d . The set of all weight functions on P has the natural structure of a polyhedral fan, the *secondary fan* SecFan(P). The rays of SecFan(P) correspond to the coarsest (regular) subdivisions of P. This paper deals with the coarsest subdivisions with precisely two maximal cells. These are called *splits*.

Hirai proved in [17] that an arbitrary weight function on P admits a canonical decomposition as a linear combination of split weights with a *split prime* remainder. This generalizes a classical result of Bandelt and Dress [2] on the decomposition of finite metric spaces, which proved to be useful for applications in phylogenomics; e.g., see Huson and Bryant [19]. We give a new proof of Hirai's split decomposition theorem which establishes the connection to the theory of secondary fans developed by Gel'fand, Kapranov, and Zelevinsky [14].

Our main contribution is the introduction and the study of the *split com*plex of a polytope P. This comes about as the clique complex of the graph

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defined by a compatibility relation on the set of splits of P. A first example is the boundary complex of the polar dual of the (n-3)-dimensional associahedron, which is isomorphic to the split complex of an n-gon. A focus of our investigation is on the hypersimplices $\Delta(k,n)$, which are the convex hulls of the 0/1-vectors of length n with exactly k ones. We classify all splits of the hypersimplices together with their compatibility relation. This describes the split complexes of the hypersimplices.

Tropical geometry is concerned with the tropicalization of algebraic varieties. An important class of examples is formed by the tropical Grassmannians $\mathcal{G}_{k,n}$ of Speyer and Sturmfels [38], which are the tropicalizations of the ordinary Grassmannians of k-dimensional subspaces of an n-dimensional vector space (over some field). It is a challenge to obtain a complete description of $\mathcal{G}_{k,n}$ even for most fixed values of k and n. A better behaved close relative of $\mathcal{G}_{k,n}$ is the tropical pre-Grassmannian pre- $\mathcal{G}_{k,n}$ arising from tropicalizing the ideal of quadratic Plücker relations. This is a subfan of the secondary fan of $\Delta(k,n)$, and its rays correspond to coarsest subdivisions of $\Delta(k,n)$ whose (maximal) cells are matroid polytopes; see Kapranov [24] and Speyer [36]. As one of our main results we prove that the split complex of $\Delta(k,n)$ is a subcomplex of pre- $\mathcal{G}'_{k,n}$, the intersection of the fan pre- $\mathcal{G}_{k,n}$ with the unit sphere in $\mathbb{R}^{\binom{n}{k}}$. Moreover, we believe that our approach can be extended further to obtain a deeper understanding of the tropical (pre-)Grassmannians. To follow this line, however, is beyond the scope of this paper.

The paper is organized as follows. We start out with the investigation of general weight functions on a polytope P and their coherence. Two weight functions are *coherent* if there is a common refinement of the subdivisions that they induce on P. As an essential technical device for the subsequent sections we introduce the *coherency index* of two weight functions on P. This generalizes the definition of Koolen and Moulton for $\Delta(2, n)$ [28, Section 4.1].

The third section then deals with splits of polytopes and the corresponding weight functions. As a first result we give a concise new proof of the split decomposition theorems of Bandelt and Dress [2, Theorem 2], and Hirai [17, Theorem 2.2].

A split subdivision of the polytope P is clearly determined by the affine hyperplane spanned by the unique interior cell of codimension 1. A set of splits is compatible if any two of the corresponding split hyperplanes do not meet in the (relative) interior of P. The split complex Split(P) is the abstract simplicial complex of compatible sets of splits of P. It is an interesting fact that the subdivision of P induced by a sum of weights corresponding to a compatible system of splits is dual to a tree. In this sense Split(P) can always be seen as a "space of trees".

In Section 5 we study the hypersimplices $\Delta(k, n)$. Their splits are classified and explicitly enumerated. Moreover, we characterize the compatible pairs of splits. The purpose of the short Section 6 is to specialize our results for arbitrary hypersimplices to the case k = 2. A metric on a finite set of n points

yields a weight function on $\Delta(2, n)$, and hence all the previous results can be interpreted for finite metric spaces. This is the classical situation studied by Bandelt and Dress [1, 2]. Notice that some of their results had already been obtained by Isbell much earlier [20].

Section 7 bridges the gap between the split theory of the hypersimplices and matroid theory. This way, as one key result, we can prove that the split complex of the hypersimplex $\Delta(k,n)$ is a subcomplex of the tropical pre-Grassmannian pre- $\mathcal{G}'_{k,n}$. We conclude the paper with a list of open questions.

2. Coherency of Weight Functions

Let $P \subset \mathbb{R}^{d+1}$ be a polytope with vertices v_1, \ldots, v_n . We form the $n \times (d+1)$ -matrix V whose rows are the vertices of P. For technical reasons we make the assumption that P is d-dimensional and that the (column) vector $\mathbb{1} := (1, \ldots, 1)$ is contained in the linear span of the columns of V. In particular, this implies that P is contained in some affine hyperplane which does not contain the origin. A weight function $w : \text{Vert } P \to \mathbb{R}$ of P can be written as a vector in \mathbb{R}^n . Now each weight function w of P gives rise to the unbounded polyhedron

$$\mathcal{E}_w(P) := \left\{ x \in \mathbb{R}^{d+1} \mid Vx \ge -w \right\} ,$$

the *envelope* of P with respect to w. We refer to Ziegler [45] for details on polytopes.

If w_1 and w_2 are both weight functions of P, then $Vx \ge -w_1$ and $Vy \ge -w_2$ implies $V(x+y) \ge -(w_1+w_2)$. This yields the inclusion

(1)
$$\mathcal{E}_{w_1}(P) + \mathcal{E}_{w_2}(P) \subseteq \mathcal{E}_{w_1 + w_2}(P).$$

If equality holds in (1) then (w_1, w_2) is called a *coherent decomposition* of $w = w_1 + w_2$. (Note that this must not be confused with the notion of "coherent subdivision" which is sometimes used instead of "regular subdivision".)

Example 2.1. We consider a hexagon $H \subset \mathbb{R}^3$ whose vertices are the columns of the matrix

$$V^{\mathsf{T}} = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 2 & 1 & 0 \\ 0 & 0 & 1 & 2 & 2 & 1 \end{pmatrix}$$

and three weight functions $w_1 = (0, 0, 1, 1, 0, 0)$, $w_2 = (0, 0, 0, 1, 1, 0)$, and $w_3 = (0, 0, 2, 3, 2, 0)$. Again we identify a matrix with the set of its rows. A direct computation then yields that $w_1 + w_2$ is not coherent, but both $w_1 + w_3$ and $w_2 + w_3$ are coherent.

Each face of a polyhedron, that is, the intersection with a supporting hyperplane, is again a polyhedron, and it can be bounded or not. A polyhedron is pointed if it does not contain an affine subspace or, equivalently, its lineality space is trivial. This implies that the set of all bounded faces is non-empty and forms a polytopal complex. This polytopal complex is always contractible (see Hirai [16, Lemma 4.5]). The polytopal complex of bounded faces of the

polyhedron $\mathcal{E}_w(P)$ is called the *tight span* of P with respect to w, and it is denoted by $\mathcal{T}_w(P)$.

Lemma 2.2. Let $w = w_1 + w_2$ be a decomposition of weight functions of P. Then the following statements are equivalent.

- (i) The decomposition (w_1, w_2) is coherent,
- (ii) $\mathfrak{T}_w(P) \subseteq \mathfrak{T}_{w_1}(P) + \mathfrak{T}_{w_2}(P)$,
- (iii) $\mathfrak{T}_w(P) \subseteq \mathcal{E}_{w_1}(P) + \mathcal{E}_{w_2}(P)$,
- (iv) each vertex of $\mathfrak{T}_w(P)$ can be written as a sum of a vertex of $\mathfrak{T}_{w_1}(P)$ and a vertex of $\mathfrak{T}_{w_2}(P)$.

For a similar statement in the special case where P is a second hypersimplex (see Section 5 below) see Koolen and Moulton [27], Lemma 1.2.

Proof. If (w_1, w_2) is coherent then by definition $\mathcal{E}_w(P) = \mathcal{E}_{w_1}(P) + \mathcal{E}_{w_2}(P)$. Each face F of the Minkowski sum of two polyhedra is the Minkowski sum of two faces F_1, F_2 , one from each summand. Now F is bounded if and only if F_1 and F_2 are bounded. This proves that (i) implies (ii).

Clearly, (ii) implies (iii). Moreover, (iii) implies (iv) by the same argument on Minkowski sums as above.

To complete the proof we have to show that (i) follows from (iv). So assume that each vertex of $\mathfrak{T}_w(P)$ can be written as a sum of a vertex of $\mathfrak{T}_{w_1}(P)$ and a vertex of $\mathfrak{T}_{w_2}(P)$, and let $x \in \mathcal{E}_w(P)$. Then x can be written as x = y + r where $y \in \mathfrak{T}_w(P)$ and r is a ray of $\mathcal{E}_w(P)$, that is, $z + \lambda r \in \mathcal{E}_w(P)$ for all $z \in \mathcal{E}_w(P)$ and all $\lambda \geq 0$. It follows that $Vr \leq 0$. By assumption there are vertices y_1 and y_2 of $\mathfrak{T}_{w_1}(P)$ and $\mathfrak{T}_{w_2}(P)$ such that $y = y_1 + y_2$. Setting $x_1 := y_1 + r$ and $x_2 := y_2$ we have $x = x_1 + x_2$ with $x_2 \in \mathcal{E}_{w_2}(P)$. Computing

$$Vx_1 = V(y_1 + r) \le Vy_1 + Vr \le -w_1 + 0 = -w_1$$

we infer that $x_1 \in \mathcal{E}_{w_1}(P)$, and hence w_1 and w_2 are coherent.

We recall basic facts about cone polarity. For an arbitrary pointed polyhedron $X \subset \mathbb{R}^{d+1}$ there exists a unique polyhedral cone $C(X) \subset \mathbb{R}^{d+2}$ such that $X = \{x \in \mathbb{R}^{d+1} \mid (1,x) \in C(P)\}$. If X is given in inequality description $X = \{x \in \mathbb{R}^{d+1} \mid Ax \geq b\}$ one has

$$C(X) = \left\{ y \in \mathbb{R}^{d+2} \ \left| \ \begin{pmatrix} 1 & 0 \\ -b & A \end{pmatrix} y \geq 0 \right\} \ .$$

If X is given in a vertex-ray description $P = \operatorname{conv} V + \operatorname{pos} R$ one has

$$C(X) = pos \begin{pmatrix} 1 & V \\ 0 & R \end{pmatrix}$$
.

For any set $M \subseteq \mathbb{R}^{d+2}$ its cone polar is defined as $M^{\circ} := \{y \in \mathbb{R}^{d+2} \mid \langle x,y \rangle \geq 0 \text{ for all } x \in M\}$. If C = pos A is a cone it is easily seen that $C^{\circ} = \{y \in \mathbb{R}^{d+2} \mid Ay \geq 0\}$ and that $(C^{\circ})^{\circ} = C$. The cone C° is called the *polar dual* cone of C. Two polyhedra X and Y are *polar duals* if the corresponding cones C(X) and C(Y) are. The face lattices of dual cones are anti-isomorphic.

For the following our technical assumptions from the beginning come into play. Again let P be a d-polytope in \mathbb{R}^{d+1} such that \mathbb{I} is contained in the column span of the matrix V whose rows are the vertices of P. The standard basis vectors of \mathbb{R}^{d+1} are denoted by e_1, \ldots, e_{d+1} .

Proposition 2.3. The polyhedron $\mathcal{E}_w(P)$ is affinely equivalent to the polar dual of the polyhedron

$$\mathcal{L}_w(P) := \text{conv} \{ v + w(v)e_{d+1} \mid v \in \text{Vert } P \} + \mathbb{R}_{>0}e_{d+1} .$$

Moreover, the face poset of $\mathfrak{T}_w(P)$ is anti-isomorphic to the face poset of the interior lower faces (with respect to the last coordinate) of $\mathcal{L}_w(P)$.

Proof. Note first, that by our assumption that $\mathbb{1}$ is in the column span of V, up to a linear transformation of \mathbb{R}^{d+1} , we can assume that $V = (\bar{V}, \mathbb{1})$ for an $n \times d$ -matrix \bar{V} . This yields

$$C(\mathcal{E}_w(P)) = \left\{ x \in \mathbb{R}^{d+2} \ \middle| \ \begin{pmatrix} 1 & 0 & 0 \\ w & \bar{V} & 1 \end{pmatrix} x \ge 0 \right\}.$$

On the other hand we have

$$C(\mathcal{L}_w(P)) = \operatorname{pos} \begin{pmatrix} \mathbb{1} & \bar{V} & w \\ 0 & 0 & 1 \end{pmatrix},$$

which is linearly isomorphic to $\bar{C} = \text{pos}\begin{pmatrix} w & 1 & \bar{V} \\ 1 & 0 & 0 \end{pmatrix}$ by a coordinate change, so $\mathcal{E}_w(P)$ and $\mathcal{L}_w(P)$ are polar duals, up to linear transformations.

This way we have obtained an anti-isomorphism of the face lattices of $C(\mathcal{E}_w(P))$ and $C(\mathcal{L}_w(P))$. A face F of $\mathcal{E}_w(P)$ is bounded if and only if no generator of $C(\mathcal{E}_w(P))$ with first coordinate equal to zero is smaller then F in the face lattice. In the dual view, this means that the corresponding face F' of $\mathcal{L}_w(P)$ is greater then a facet which is parallel to the last coordinate axis in the face lattice of $C(\mathcal{L}_w(P))$. But this exactly means that F' is a lower face. So the lattice anti-isomorphism of $C(\mathcal{E}_w(P))$ and $C(\mathcal{L}_w(P))$ induces a poset anti-isomorphism between $\mathcal{T}_w(P)$ and the interior lower faces of $\mathcal{L}_w(P)$.

The lower faces of $\mathcal{L}_w(P)$ (with respect to the last coordinate) are precisely its bounded faces. By projecting back to aff P in the e_{d+1} -direction, the polytopal complex of bounded faces of $\mathcal{L}_w(P)$ induces a polytopal decomposition $\Sigma_w(P)$ of P. Note that we only allow the vertices of P as vertices of any subdivision of P. A polytopal subdivision which arises in this way is called *regular*. Two weight functions are *equivalent* if they induce the same subdivision. This allows for one more characterization extending Lemma 2.2.

Corollary 2.4. A decomposition $w = w_1 + w_2$ of weight functions of P is coherent if and only if the subdivision $\Sigma_w(P)$ is the common refinement of the subdivisions $\Sigma_{w_1}(P)$ and $\Sigma_{w_2}(P)$.

Proof. By Lemma 2.2, the decomposition $w_1 + w_2$ is coherent if and only if each vertex x of $\mathfrak{T}_w(P)$ is the sum of a vertex x_1 of $\mathfrak{T}_{w_1}(P)$ and a vertex x_2 of $\mathfrak{T}_{w_2}(P)$. In terms of the duality proved in Proposition 2.3 the vertex x

corresponds to the maximal cell $F_w(x) := \text{conv}\{v \in \text{Vert } P \mid \langle v, x \rangle = -w\}$ of $\Sigma_w(P)$. Similarly, x_1 and x_2 corresponds to the cells $F_{w_1}(x_1)$ and $F_{w_2}(x_2)$ of $\Sigma_{w_1}(P)$ and $\Sigma_{w_2}(P)$, respectively. In fact, we have $F_w(x) = F_{w_1}(x_1) \cap F_{w_2}(x_2)$, and so $\Sigma_w(P)$ is the common refinement of $\Sigma_{w_1}(P)$ and $\Sigma_{w_2}(P)$. The converse follows similarly.

Example 2.5. In Example 2.1 the tight spans of the three weight functions of the hexagon are line segments:

$$\begin{split} & \mathfrak{T}_{w_1}(H) = [0, (1, -1, 0)] \\ & \mathfrak{T}_{w_2}(H) = [0, (1, 0, -1)] \\ & \mathfrak{T}_{w_3}(H) = [0, (1, -1, -1)]. \end{split}$$

Remark 2.6. Interesting special cases of tight spans include the following. Finite metric spaces (on n points) give rise to weight functions on the second hypersimplex $P = \Delta(2, n)$. In this case the tight span can be interpreted as a "space" of trees which are candidates to fit the given metric. This has been studied by Bandelt and Dress [2], and this is the context in which the name "tight span" was used first. See also Section 6 below.

If P is a product of two simplices, the tight span of a lifting function gives rise to a *tropical polytope* introduced by Develin and Sturmfels [9], the cells in the resulting regular decomposition of P are the *polytropes* of [23].

If P spans the affine hyperplane $x_1=1$ and if we consider the weight function defined by $w(v)=v_2^2+v_3^2+\cdots+v_{d+1}^2$ for each vertex v of P then the tight span $\mathfrak{T}_w(P)$ is isomorphic to the subcomplex of bounded faces of the Voronoi diagram of Vert P. All maximal cells of the Voronoi diagram are unbounded and hence the tight span is at most (d-1)-dimensional. The subdivision $\Sigma_w(P)$ is then isomorphic to the Delone decomposition of Vert P.

Let w and w' be weight functions of our polytope P. We want to have a measure which expresses to what extent the pair of weight functions (w', w-w') deviates from coherence (if at all). The *coherency index* of w with respect to w' is defined as

$$(2) \qquad \alpha_{w'}^{w} := \min_{x \in \operatorname{Vert} \mathcal{E}_{w}(P)} \left\{ \max_{x' \in \operatorname{Vert} \mathcal{E}_{w'}(P)} \left\{ \min_{v \in V_{w'}(x')} \left\{ \frac{\langle v, x \rangle + w(v)}{\langle v, x' \rangle + w'(v)} \right\} \right\} \right\},$$

where $V_{w'}(x') = \{v \in \text{Vert } P \mid \langle v, x' \rangle \neq -w'(v)\}$. (That is, $V_{w'}(x')$ is the set of vertices of P that are not contained in the cell dual to x.) The name is justified by the following observation which generalizes Koolen and Moulton [28, Theorem 4.1].

Proposition 2.7. Let w and w' be weight functions of the polytope P. Moreover, let $\lambda \in \mathbb{R}$ and $\tilde{w} := w - \lambda w'$. Then $w = \tilde{w} + \lambda w'$ is coherent if and only if $0 \le \lambda \le \alpha_{w'}^w$.

Proof. Assume that $w = \tilde{w} + \lambda w'$ is coherent. By Lemma 2.2 for each vertex x of $\mathcal{E}_w(P)$ there is a vertex x' of $\mathcal{E}_{w'}(P)$ such that $x - \lambda x'$ is a vertex of $\mathcal{E}_{\tilde{w}}(P)$.

We arrive at the following sequence of equivalences:

$$x - \lambda x' \in \mathfrak{I}_{\tilde{w}}(P) \iff -w(v) + \lambda w'(v) \leq \langle v, x - \lambda x' \rangle \quad \text{for all } v \in \text{Vert } P$$

$$\iff \lambda(\langle v, x' \rangle + w'(v)) \leq \langle v, x \rangle + w(v) \quad \text{for all } v \in \text{Vert } P$$

$$\iff \lambda \leq \frac{\langle v, x \rangle + w(v)}{\langle v, x' \rangle + w'(v)} \quad \text{for all } v \in V_{w'}(x')$$

$$\iff \lambda \leq \min_{v \in V_{w'}(x')} \left\{ \frac{\langle v, x \rangle + w(v)}{\langle v, x' \rangle + w'(v)} \right\}.$$

For each vertex x of $\mathcal{E}_w(P)$ there must be some vertex x' of $\mathcal{E}_{w'}(P)$ such that these inequalities hold, and this gives the claim.

Corollary 2.8. For two weight function w and w' of P we have

$$\alpha_{w'}^w = \sup \{ \lambda \geq 0 \mid (w - \lambda w', \lambda w') \text{ is a coherent decomposition of } w \}.$$

Corollary 2.9. If w and w' are weight functions then $\Sigma_w(P) = \Sigma_{w'}(P)$ if and only if $\alpha_{w'}^w > 0$ and $\alpha_w^{w'} > 0$.

The set of all regular subdivisions of the convex polytope P is known to have an interesting structure (see [7, Chapter 5] for the details): For a weight function $w \in \mathbb{R}^n$ of P we consider the set $S[w] \subset \mathbb{R}^n$ of all weight functions that are equivalent to w, that is,

$$S[w] := \{ x \in \mathbb{R}^n \mid \Sigma_x(P) = \Sigma_w(P) \} .$$

This set is called the *secondary cone* of P with respect to w. It can be shown (for instance, see [7, Corollary 5.2.10]) that S[w] is indeed a polyhedral cone and that the set of all S[w] (for all w) forms a polyhedral fan SecFan(P), called the *secondary fan* of P.

It is easily verified that S[0] is the set of all (restrictions of) affine linear functions and that it is the lineality space of every cone in the secondary fan. So this fan can be regarded in the quotient space $\mathbb{R}^n/S[0] \cong \mathbb{R}^{n-d-1}$. If there is no change for confusion we will identify $w \in \mathbb{R}^n$ and its image in $\mathbb{R}^n/S[0]$. Furthermore, the secondary fan can be cut with the unit sphere to get a (spherical) polytopal complex on the set of rays in the fan. This complex carries the same information as the fan itself and will also be identified with it.

It is a famous result by Gel'fand, Kapranov, and Zelevinsky [14, Theorem 1.7], that the secondary fan is the normal fan of a polytope, the secondary polytope SecPoly(P) of P. This polytope admits a realization as the convex hull of the so-called GKZ-vectors of all (regular) triangulations. The GKZ-vector $x_{\Delta} \in \mathbb{R}^n$ of a triangulation Δ is defined as $(x_{\Delta})_v := \sum_S \text{Vol } S$ for all $v \in \text{Vert } P$, where the sum ranges over all full-dimensional simplices $S \in \Delta$ which contain v.

A description in terms of inequalities is given by Lee [30, Section 17.6, Result 4]: The affine hull of $SecPoly(P) \subset \mathbb{R}^n$ is given by the d+1 equations

(3)
$$\sum_{v \in \text{Vert } P} x_v = (d+1)d \operatorname{Vol} P \text{ and }$$
$$\sum_{v \in \text{Vert } P} x_v v = ((d+1) \operatorname{Vol} P) c_P,$$

where c_P denotes the centroid of P and Vol denotes the d-dimensional volume in the affine span of P, which we can identify with \mathbb{R}^d . The facet defining inequalities of SecPoly(P) are

(4)
$$\sum_{v \in \text{Vert } P} w(v)x_v \ge (d+1) \sum_{Q \in \Sigma_w(P)} \text{Vol } Q\bar{w}(c_Q),$$

for all coarsest regular subdivisions $\Sigma_w(P)$ defined by a weight w. Here $\bar{w}: P \mapsto \mathbb{R}$ denotes the piecewise-linear convex function whose graph is given by the lower facets of $\mathcal{L}_w(P)$.

A weight function w such that for all weight functions w' with $\alpha_{w'}^w > 0$ we have $w' = \lambda w$ (in $\mathbb{R}^n/S[0]$) for some $\lambda > 0$ is called *prime*. The set of all prime weight functions for a given polytope P is denoted $\mathcal{W}(P)$. By this we get directly:

Proposition 2.10. The equivalence classes of prime weights correspond to the extremal rays of the secondary fan (and hence to the coarsest regular subdivisions or, equivalently, to the facets of the secondary polytope).

The following is a reformulation of the fact that the set of all equivalence classes of weight functions forms a fan (the secondary fan).

Theorem 2.11. Each weight function w on a polytope P can be decomposed into a coherent sum of prime weight functions, that is, there are $p_1, \ldots, p_k \in W(P)$ such that $w = p_1 + \cdots + p_k$ is a coherent decomposition.

Proof. Each weight function w is contained in some cone of the secondary fan of P. Hence there are extremal rays r_1, \ldots, r_k of the secondary cone and positive real numbers $\lambda_1, \ldots, \lambda_k$ such that $w = \lambda_1 r_1 + \cdots + \lambda_k r_k$; by construction, this decomposition is coherent by Lemma 2.2. From Proposition 2.10 we know that $p_i := \lambda_i r_i$ is a prime weight, and the claim follows.

Note that this decomposition is usually not unique.

3. Splits and the Split Decomposition Theorem

A split S of a polytope P is a decomposition of P without new vertices which has exactly two maximal cells denoted by S_+ and S_- . As above, we assume that $P \subset \mathbb{R}^{d+1}$ is d-dimensional and that aff P does not contain the origin. Then the linear span of $S_+ \cap S_-$ is a linear hyperplane H_S , the split hyperplane of S with respect to P. Since S does not induce any new vertices, in particular, H_S does not meet any edge of P in its relative interior. Conversely,

each hyperplane which separates P and which does not separate any edge defines a split of P. Furthermore, it is easy to see, that a hyperplane defines a split of P if and only if it defines a split on all facets of P that it meets in the interior.

The following observation is immediate. Note that it implies that a hyperplane defines a split if and only if its does not separate any edge.

Observation 3.1. A hyperplane that meets P in its interior is a split hyperplane of P if and only if it intersects each of its facets F in either a split hyperplane of F or in a face of F.

Remark 3.2. Since the notion of facets and faces of a polytope does only depend on the *oriented matroid* of P it follows from Observation 3.1 that the set splits of a polytope only depend on the oriented matroid of P. This is in contrast to the fact that the set of regular triangulations (see below), in general, depends on the specific coordinatization.

The running theme of this paper is: If a polytope admits sufficiently many splits then interesting things happen. However, one should keep in mind that there are many polytopes without a single split; such polytopes are called *unsplittable*.

Remark 3.3. If v is a vertex of P such that all neighbors of v in P are contained in a common hyperplane H_v then H_v defines a split S_v of P. Such a split is called the *vertex split* with respect to v. For instance, if P is simple then each vertex defines a vertex split.

Since polygons are simple polytopes it follows, in particular, that an unsplittable polytope which is not a simplex is at least 3-dimensional. An unsplittable 3-polytope has at least six vertices. An example is a 3-dimensional cross polytope whose vertices are perturbed into general position.

Proposition 3.4. Each 2-neighborly polytope is unsplittable.

Proof. Assume that S is a split of P, and P is 2-neighborly. Recall that the latter property means that any two vertices of P are joined by an edge. Choose vertices $v \in S_+ \setminus S_-$ and $w \in S_- \setminus S_+$. Then the segment [v, w] is an edge of P which is separated by the split hyperplane H_S . This is a contradiction to the assumption that S was a split of P.

It is clear that splits yield coarsest subdivisions; but the following lemma says that they even define facets of the secondary polytope.

Lemma 3.5. Splits are regular.

Proof. Let S be a split of P. We have to show that S is induced by a weight function. Let a be a normal vector of the split hyperplane H_S . We define $w_S : \text{Vert}(P) \to \mathbb{R}$ by

(5)
$$w_S(v) := \begin{cases} |av| & \text{if } v \in S_+ \\ 0 & \text{if } v \in S_- \end{cases},$$

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Note that this function is well-defined since for $v \in H_S = \lim(S_+ \cap S_-)$ we have av = 0. It is now obvious that w induces the split S on P.

Example 3.6. In Example 2.1 the three weight functions w_1 , w_2 , w_3 define splits of the hexagon H.

By specializing Equation (4), a facet defining inequality for the split S is given by

(6)
$$\sum_{v \in \operatorname{Vert}(S_{+})} |av| x_{v} \ge |ac_{S_{+}}| (d+1) \operatorname{Vol}(S_{+}).$$

Note that a is a normal vector of the split hyperplane H_S as above, and c_{S_+} is the centroid of the polytope S_+ . By taking the inequalities (6) for all splits S of P together with the equations (3) we get an (n-d-1)-dimensional polyhedron SplitPoly(P) which we will call the *split polyhedron* of P. Obviously, we have SecPoly(P) \subseteq SplitPoly(P) so the split polyhedron can be seen as an outer "approximation" of the secondary polytope. In fact, by Remark 3.2, SplitPoly(P) is a common "approximation" for the secondary polytopes of all possible coordinatizations of the oriented matroid of P. If P has sufficiently many splits the split polyhedron is bounded; in this case SplitPoly(P) is called the *split polytope* of P.

One can show that each simple polytope has a bounded split polyhedron. Here we give two examples.

Example 3.7. Let P be a an n-gon for $n \geq 4$. Then each pair of non-neighboring vertices defines a split of P. Each triangulation is regular and, moreover, a split triangulation.

The secondary polytope of P is the associahedron Assoc_{n-3} , which is a simple polytope of dimension n-3. Since the only coarsest subdivisions of P are the splits it follows that the split polytope of P coincides with its secondary polytope.

Example 3.8. The 74 triangulations of the regular 3-cube $C_3 = [-1, 1]^3$ are all regular, and 26 of them are induced by splits. The total number of splits is 14: There are eight vertex splits (C being simple) and six splits defined by parallel pairs of diagonals in an opposite pair of cube facets. The secondary polytope of C is a 4-polytope with f-vector (74, 152, 100, 22); see Pfeifle [32] for a complete description.

The split polytope of C_3 is neither simplicial nor simple and has the f-vector (22, 60, 52, 14). A Schlegel diagram is shown in Figure 1.

Example 3.9. There are nearly 88 million regular triangulations of the 4-cube $C_4 = [-1, 1]^4$ that come in 235,277 equivalence classes. The 4-cube has four different types of splits: The vertex splits, the split obtained by cutting with $H := \{x \mid \sum x_i = 0\}$ (and its images under the symmetry group of the cube), and, finally, two kinds of splits induced by the two kinds of splits of the 3-cube. The split obtained from the vertex split of the 3-cube is the one discussed in [18, Example 20 (The missing split)]. See also [18] for a complete discussion of

the secondary polytope of C_4 . Examples of triangulations of the 4-cube that are induced by splits include the first two in [18, Example 10 & Figure 3] and the one shown in Figure 4.

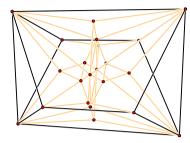


FIGURE 1. Schlegel diagram of the split polytope of the regular 3-cube.

A weight function w on a polytope P is called *split prime* if for all splits S of P we have $\alpha_{w_S}^w = 0$. The following can be seen as a generalization of Bandelt and Dress [2, Theorem 2], and as a reformulation of Hirai's Theorem 2.2 [17].

Theorem 3.10 (Split Decomposition Theorem). Each weight function w has a coherent decomposition

(7)
$$w = w_0 + \sum_{S \text{ split of } P} \lambda_S w_S,$$

where w_0 is split prime, and this is unique among all coherent decompositions of w.

This is called the *split decomposition* of w.

Proof. We first consider the special case where the subdivision $\Sigma_w(P)$ induced by w is a common refinement of splits. Then each face F of codimension 1 in $\Sigma_w(P)$ defines a unique split S(F), namely the one with split hyperplane $H_{S(F)} = \lim F$. Moreover, whenever S is an arbitrary split of P then $\alpha_{w_S}^w > 0$ if and only if $H_S \cap P$ is a face of $\Sigma_w(P)_w$ of codimension 1. This gives a coherent subdivision $w = \sum_S \alpha_{w_S}^w w_S$, where the sum ranges over all splits S of P. Note that the uniqueness follows from the fact that for each codimension-1-faces of $\Sigma_w(P)_w$ there is a unique split which coarsens it.

For the general case, we let

$$w_0 := w - \sum_{S \text{ split of } P} \alpha_{w_S}^w w_S.$$

By construction, w_0 is split prime, and the uniqueness of the split decomposition of w follows from the uniqueness of the split decomposition of $w-w_0$.

In fact, the sum in (7) only runs over all splits in $S(w) := \{w_S \mid \alpha_{w_S}^w > 0\}$. The uniqueness part of the theorem gives us the following interesting corollary (see also Bandelt and Dress [2, Corollary 5], and Hirai [17, Proposition 3.6]):

Corollary 3.11. For a weight function w the set $S(w) \cup \{w_0\}$ is linearly independent. In particular, $\#S(w) \le n - d - 1$, if #S(w) = n - d - 1 then $w_0 = 0$, and if #S(w) = n - d - 2 then w_0 is a prime weight function.

Proof. Suppose the set would be linearly dependent. This would yield a relation

$$\sum_{S \in \mathbb{S}} \lambda_S w_S = \lambda_0 w_0 + \sum_{S \in \mathbb{S}(w) \setminus \mathbb{S}} \lambda_S w_S$$

with coefficients $\lambda_0, \lambda_S \geq 0$ for some $S \subset S(w)$. However, this contradicts the uniqueness part of Theorem 3.10 for the weight function $w' := \sum_{S \in S} \lambda_S w_S$.

The cardinality constraints now follow from the fact that the weight functions live in $\mathbb{R}^n/S[0] \cong \mathbb{R}^{n-d-1}$.

The next lemma is a specialization of Corollary 2.4 to the case of splits and their weight functions.

Lemma 3.12. Let S be a set of splits for P. Then the following statements are equivalent.

- (i) The corresponding decomposition $w := \sum_{S \in \mathcal{S}} w_S$ is coherent,
- (ii) there exists a common refinement of all $S \in S$ (induced by w),
- (iii) there is a regular triangulation of P which refines all $S \in S$.

Instead of "set of splits" we equivalently use the term split system. A split system is called weakly compatible if one of the properties of Lemma 3.12 is satisfied. Moreover, two splits S_1 and S_2 such that $H_{S_1} \cap H_{S_2}$ does not meet P in its interior are called compatible. This notion generalizes to arbitrary split systems in different ways: A set S of splits is called compatible if any two of its splits are compatible. It is incompatible if it is not compatible, and it is totally incompatible if any two of its splits are incompatible. It is clear that total incompatibility implies incompatibility, and that compatibility implies weak compatibility (but the converse does not hold, see Example 4.10).

For an arbitrary split system S we define its weight function as

$$w_{\mathcal{S}} := \sum_{S \in \mathcal{S}} w_S.$$

If S is weakly compatible then $\Sigma_{S}(P) := \Sigma_{w_{S}}(P)$ is the coarsest subdivision refining all splits in S. We further abbreviate $\mathcal{E}_{S}(P) := \mathcal{E}_{w_{S}}(P)$ and $\mathcal{T}_{S}(P) := \mathcal{T}_{w_{S}}(P)$.

Remark 3.13. The split decomposition (7) of a weight function w of the d-polytope P can actually be computed using our formula (2). Provided we already know the, say, t vertices of the tight span of w and the, say, t splits of t, this takes t (or the rationals), where t = t Vert t ve

4. Split Complexes and Split Subdivisions

Let P be a fixed d-polytope, and let $\mathcal{S}(P)$ be the set of all splits of P. The notions of compatibility and weak compatibility of splits give rise to two abstract simplicial complexes with vertex set $\mathcal{S}(P)$. We denote them by $\mathrm{Split}(P)$ and $\mathrm{Split}^{\mathrm{w}}(P)$, respectively. Since compatibility implies weak compatibility $\mathrm{Split}(P)$ is a subcomplex of $\mathrm{Split}^{\mathrm{w}}(P)$. Moreover, if $\mathcal{S}\subseteq\mathcal{S}(P)$ is a split system such that any two splits in \mathcal{S} are compatible then the whole split system \mathcal{S} is compatible. This can also be phrased in graph theory language: The compatibility relation among the splits defines an undirected graph, whose cliques correspond to the faces of $\mathrm{Split}(P)$. In particular, we have the following:

Proposition 4.1. The split complex Split(P) is a flag simplicial complex.

Note that we did not assume that P admits any split. If P is unsplittable then the (weak) split complex of P is the void complex \varnothing .

Theorem 3.10 tells us that the fan spanned by the rays that induce splits is a simplicial fan contained in (the support of) $\operatorname{SecFan}(P)$. This fan was called the *split fan* of P by Koichi [26]. Denoting by $\operatorname{SecFan}'(P)$ the (spherical) polytopal complex which arises from $\operatorname{SecFan}(P)$ by intersecting with the unit sphere, this leads to the following observation:

Corollary 4.2. The simplicial complex Split(P) is a subcomplex of the polytopal complex SecFan'(P).

Proof. The tight span of a compatible system S of splits of P is a tree by Proposition 4.6. This implies that the cell C in SecFan'(P) generated by S does not contain vertices whose tight span is of dimension greater than one. Thus the vertices of C are precisely the splits in S.

Remark 4.3. The weak split complex of P is usually not a subcomplex of SecFan'(P); see Example 4.10. However, one can show that $Split^{w}(P)$ is homotopy equivalent to a subcomplex of SecFan'(P).

From Corollary 3.11 we can trivially derive an upper bound on the dimensions of the split complex and the weak split complex. This bound is sharp for both types of complexes as we will see in Example 4.8 below.

Proposition 4.4. The dimensions of Split(P) and $Split^{w}(P)$ are bounded from above by n - d - 2.

A regular subdivision (triangulation) Σ of P is called a *split subdivision* (triangulation) if it is the common refinement of a set S of splits of P. Necessarily, the split system S is weakly compatible, and S is a face of $Split^w(P)$. Conversely, all faces of $Split^w(P)$ arise in this way.

Corollary 4.5. If S is a facet of $Split^{w}(P)$ with #S = n - d - 1 then the split subdivision $\Sigma_{S}(P)$ is a split triangulation.

Proof. Corollary 3.11 implies that $W := \{w_S \mid S \in \mathbb{S}\}$ is linearly independent and hence a basis of $\mathbb{R}^n/S[0] \cong \mathbb{R}^{n-d-1}$. So the cone spanned by W is full-dimensional and hence corresponds to a vertex of the secondary polytope. \square

The following is a characterization of the faces of Split(P), and it says that split complexes are always "spaces of trees".

Proposition 4.6 (Hirai [17], Proposition 2.9). Let S be a split system on P. Then the following statements are equivalent.

- (i) S is compatible,
- (ii) $T_S(P)$ is 1-dimensional, and
- (iii) $\mathfrak{T}_{S}(P)$ is a tree.

Proof. Assume that $\Sigma_{\mathbb{S}}(P)$ is induced by the compatible split system $\mathbb{S} \neq \emptyset$. By definition, for any two distinct splits $S_1, S_2 \in \mathbb{S}$ the hyperplanes H_{S_1} and H_{S_2} do not meet in the interior of P. This implies that there are no interior faces in $\Sigma_{\mathbb{S}}(P)$ of codimension greater than 1. By Proposition 2.3, this says that $\dim \mathfrak{T}_{\mathbb{S}}(P) \leq 1$. Since $\mathbb{S} \neq \emptyset$ we have that $\dim \mathfrak{T}_{\mathbb{S}}(P) = 1$. Thus (i) implies (ii).

The statement (iii) follows from (ii) as the tight span is contractible.

Suppose that $\mathcal{T}_{\mathbb{S}}(P)$ is a tree. Then each edge is dual to a split hyperplane. The system \mathbb{S} of all these splits is clearly weakly compatible since it is refined by $\Sigma_{\mathbb{S}}(P)$. Assume that there are splits $S_1, S_2 \in \mathbb{S}$ such that the corresponding split hyperplanes H_{S_1} and H_{S_2} meet in the interior of P. Then $H_{S_1} \cap H_{S_2}$ is an interior face in $\Sigma_{\mathbb{S}}(P)$ of codimension 2, contradicting our assumption that $\mathcal{T}_{\mathbb{S}}(P)$ is a tree. This proves (i), and hence the claim follows.

Remark 4.7. A d-dimensional polytope is called stacked if it has a triangulation in which there are no interior faces of dimension less than d-1. So it follows from Proposition 4.6 that a polytope is stacked if and only if there exists a split triangulation induced by a compatible system of splits.

Example 4.8. Let P be a an n-gon for $n \ge 4$. As already pointed out in Example 3.7, each pair of non-neighboring vertices defines a split of P. Two such splits are compatible if and only if they are weakly compatible.

The secondary polytope of P is the associahedron $\operatorname{Assoc}_{n-3}$, and the split complex of P is isomorphic to the boundary complex of its dual. In particular, $\operatorname{Split}(P) = \operatorname{Split}^{\operatorname{w}}(P)$ is a pure and shellable simplicial complex of dimension n-4, which is homeomorphic to \mathbb{S}^{n-4} . This shows that the bound in Proposition 4.4 is sharp. From Catalan combinatorics it is known that the (split) triangulations of P correspond to the binary trees on n-2 nodes; see [7, Section 1.1].

Example 4.9. The splits of the regular cross polytope $X_d = \text{conv}\{\pm e_1, \pm e_2, \ldots, \pm e_d\}$ in \mathbb{R}^d are induced by the d reflection hyperplanes $x_i = 0$. Any d-1 of them are weakly compatible and define a triangulation of X_d by Corollary 4.5. (Of course, this can also be seen directly.) All triangulations of X_d arise in this way. This shows that $\text{Split}^w(X_d)$ is isomorphic to the boundary complex of a (d-1)-dimensional simplex, which is also the secondary polytope and the split polytope of X_d . Any two reflection hyperplanes meet in the interior of X_d , whence no two splits are compatible. This says that $\text{Split}(X_d)$ consists of d isolated points.

Example 4.10. As we already discussed in Example 3.8 the regular 3-cube $C_3 = [-1, 1]^3$ has a total number of 14 splits. The split complex $\operatorname{Split}(C)$ is 3-dimensional but not pure; its f-vector reads (14, 40, 32, 2). The two 3-dimensional facets correspond to the two non-unimodular triangulations of C (arising from splitting every other vertex). The reduced homology is concentrated in dimension two, and we have $H_2(\operatorname{Split}(C_3); \mathbb{Z}) \cong \mathbb{Z}^3$. The graph indicating the compatibility relation among the splits is shown in Figure 2.

Figure 3 shows three triangulations of C_3 . The left one is generated by a totally incompatible system of three splits; that is, it is a facet of $Split^w(C_3)$ which is not a face of $Split(C_3)$. The right one is (not unimodular and) generated by a compatible split system (of four vertex splits); that is, it is a facet of both $Split(C_3)$ and $Split^w(C_3)$. The middle one is not generated by splits at all.

The triangulation Δ on the left uses only three splits. This examples shows that the converse of Corollary 4.5 is not true, that is, a weakly compatible split system that defines a triangulation does not have to be maximal with respect to cardinality. Furthermore, the triangulation Δ can also be obtained as the common refinement of two non-split coarsest subdivisions. The cell in SecFan'(C_3) corresponding to Δ is a bipyramid over a triangle. The vertices of this triangle (which is not a face of SecFan'(C_3)) correspond to the three splits, so the relevant cell in Split^w(C_3) is a triangle, and the apices corresponds to the non-split coarsest subdivisions mentioned above. Since the three splits are totally incompatible there does not exist a corresponding face in Split(C_3), and the intersection with Split(C_3) consists of three isolated points.

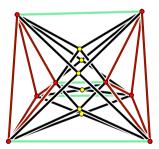


FIGURE 2. Compatibility graph of the splits of the regular 3-cube. The four (red) nodes to the left and the four (red) nodes to the right correspond to the vertex splits.

A polytopal complex is zonotopal if each face is zonotope. A zonotope is the Minkowski sum of line segments or, equivalently, the affine projection of a regular cube. Any graph, that is, a 1-dimensional polytopal complex, is zonotopal in a trivial way. So especially tight spans of splits and, by Proposition 4.6, of compatible splits systems are zonotopal. In fact, this is even true for arbitrary

weakly compatible splits systems. See also Bolker [5, Theorem 6.11] and Hirai [17, Corollary 2.8].

Theorem 4.11. Let S be a weakly compatible split system on P. Then the tight span $T_S(P)$ is a (not necessarily pure) zonotopal complex.

Proof. Let F be a face of $\mathcal{T}_{8}(P)$. Since by Lemma 3.12 we have that $\mathcal{E}_{8}(P) = \sum_{S \in \mathbb{S}} \mathcal{E}_{w_{S}}(P)$ we get (by the same arguments used in the proof of Lemma 2.2) that $F = \sum_{S \in \mathbb{S}} F_{S}$ for faces F_{S} of $\mathcal{T}_{w_{S}}(P)$. The claim now follows from the fact that $\mathcal{T}_{w_{S}}(P)$ is a line segment for all $S \in \mathbb{S}$.

A triangulation of a d-polytope is foldable if its vertices can be colored with d colors such that each edge of the triangulation receives two distinct colors. This is equivalent to requiring that the dual graph of the triangulation is bipartite; see [22, Corollary 11]. Note that foldable simplicial complexes are called "balanced" in [22]. The three triangulations of the regular 3-cube in Figure 3 are foldable.

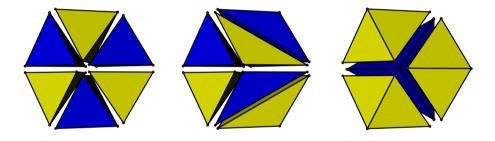


FIGURE 3. Three foldable triangulations of the regular 3-cube.

Corollary 4.12. Each split triangulation is foldable.

Proof. Let S be a weakly compatible split system such that $\Sigma_{S}(P)$ is a triangulation. By Theorem 4.11 each 2-dimensional face of the tight span $\mathfrak{T}_{S}(P)$ has an even number of vertices. This implies that $\Sigma_{S}(P)$ is a triangulation of P such that each of its interior codimension-2-cell is contained in an even number of maximal cells. Now the claim follows from [22, Corollary 11].

Example 4.13. Let C_4 be the 4-dimensional cube. In Figure 4 there is a picture of the tight span $\mathcal{T}_{\mathcal{S}}(C_4)$ of a split system \mathcal{S} of C_4 with 10 weakly compatible splits. As proposed by Theorem 4.11 the complex is zonotopal. It is 3-dimensional and its f-vector reads (24, 36, 14, 1). The number of vertices equals 24 = 4! which is the normalized volume of C_4 , and hence $\Sigma_{\mathcal{S}}(C_4)$ is, in fact, a triangulation. By Corollary 4.12 this triangulation is foldable.

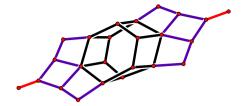


FIGURE 4. The tight span of a split triangulation of the 4-cube.

5. Hypersimplices

As a notational shorthand we abbreviate $[n] := \{1, 2, ..., n\}$ and $\binom{[n]}{k} := \{X \subseteq [n] \mid \#X = k\}$. The k-th hypersimplex in \mathbb{R}^n is defined as

$$\Delta(k,n) := \left\{ x \in [0,1]^n \; \left| \; \sum_{i=1}^n x_i = k \right. \right\} = \operatorname{conv} \left\{ \sum_{i \in A} e_i \; \left| \; A \in \binom{[n]}{k} \right. \right\} \, .$$

It is (n-1)-dimensional and satisfies the conditions of Section 2. Throughout the following we assume that $n \ge 2$ and $1 \le k \le n-1$.

A hypersimplex $\Delta(1,n)$ is an (n-1)-dimensional simplex. For arbitrary $k \geq 1$ we have $\Delta(k,n) \cong \Delta(n-k,n)$. Moreover, for $p \in [n]$ the equation $x_p = 0$ defines a facet isomorphic to $\Delta(k,n-1)$. And, if $k \geq 2$, the equation $x_p = 1$ defines a facet isomorphic to $\Delta(k-1,n)$. This list of facets (induced by the facets of $[0,1]^n$) is exhaustive. Since the hypersimplices are not full-dimensional, the facet defining (affine) hyperplanes are not unique. For the following it will be convenient to work with linear hyperplanes. This way $x_p = 1$ gets replaced by

(8)
$$(k-1)x_p = \sum_{i \in [n] \setminus \{p\}} x_i.$$

The triplet $(A, B; \mu)$ with $\emptyset \neq A, B \subsetneq [n], A \cup B = [n], A \cap B = \emptyset$ and $\mu \in \mathbb{N}$ defines the linear equation

(9)
$$\mu \sum_{i \in A} x_i = (k - \mu) \sum_{i \in B} x_i.$$

The corresponding (linear) hyperplane in \mathbb{R}^n is called the $(A, B; \mu)$ -hyperplane. Clearly, $(A, B; \mu)$ and $(B, A; k - \mu)$ define the same hyperplane. The Equation (8) corresponds to the $(\{p\}, [n] \setminus \{p\}; k-1)$ -hyperplane.

Lemma 5.1. The $(A, B; \mu)$ -hyperplane is a split hyperplane of $\Delta(k, n)$ if and only if $k - \mu + 1 \le \#A \le n - \mu - 1$ and $1 \le \mu \le k - 1$.

Proof. It is clear that the $(A, B; \mu)$ -hyperplane does not meet the interior of $\Delta(k, n)$ if $\mu \leq 0$ or if $\mu \geq k$. Especially, we may assume that $k \geq 2$.

Suppose now that $\#A \leq k-\mu$. Then each point $x \in \Delta(k,n)$ satisfies $\sum_{i \in A} x_i \leq k-\mu$ and $\sum_{i \in B} x_i \geq k-(k-\mu) = \mu$. This implies that $\mu \sum_{i \in A} x_i \leq k-\mu$

 $(k-\mu)\sum_{i\in B} x_i$, which says that all points in $\Delta(k,n)$ are contained in one of the two halfspaces defined by the $(A,B;\mu)$ -hyperplane. Hence it does not define a split. A similar argument shows that $\#A \leq n-\mu-1$ is necessary in order to define a split.

Conversely, assume that $k - \mu + 1 \le \#A \le n - \mu - 1$ and $1 \le \mu \le k - 1$. We define a point $x \in \Delta(k, n)$ by setting

$$x_i := \begin{cases} \frac{k-\mu}{\#A} & \text{if } i \in A \\ \frac{\mu}{\#B} & \text{if } i \in B . \end{cases}$$

Since $0 < \frac{k-\mu}{\#A} < 1$ and $0 < \frac{\mu}{\#B} < 1$ the point x is contained in the (relative) interior of $\Delta(k, n)$. Moreover, x satisfies the Equation (9), and so the $(A, B; \mu)$ -hyperplane passes through the interior of $\Delta(k, n)$.

It remains to show that the $(A, B; \mu)$ -hyperplane does not separate any edge. Let v and w be two adjacent vertices. So we have some $\{p,q\} \in {[n] \choose 2}$ with $v-w=e_p-e_q$. Aiming at an indirect argument, we assume that v and w are on opposite sides of the $(A, B; \mu)$ -hyperplane, that is, without loss of generality $\mu \sum_{i \in A} v_i > (k-\mu) \sum_{i \in B} v_i$ and $\mu \sum_{i \in A} w_i < (k-\mu) \sum_{i \in B} w_i$. This gives

$$0 < \mu \sum_{i \in A} v_i - (k - \mu) \sum_{i \in B} v_i = \mu(\chi_A(p) - \chi_A(q))$$

and

$$0 < (k - \mu) \sum_{i \in B} w_i - \mu \sum_{i \in A} w_i = (k - \mu)(\chi_B(p) - \chi_B(q)),$$

where characteristic functions are denoted as $\chi_{\cdot}(\cdot)$. Since $\mu > 0$ and $\mu < k$ it follows that $\chi_{A}(q) < \chi_{A}(p)$ and $\chi_{B}(q) < \chi_{B}(p)$. Now the characteristic functions take values in $\{0,1\}$ only, and we arrive at $\chi_{A}(q) = \chi_{B}(q) = 0$ and $\chi_{A}(p) = \chi_{B}(p) = 1$. Both these equations contradict the fact that (A, B) is a partition of [n]. So we conclude that, indeed, the $(A, B; \mu)$ -hyperplane defines a split.

This allows to characterize the splits of the hypersimplices.

Proposition 5.2. Each split hyperplane of $\Delta(k, n)$ is defined by a linear equation of the type (9).

Proof. Using Observation 3.1 and exploiting the fact that facets of hypersimplices are hypersimplices we can proceed by induction on n and k as follows.

Our induction is based on the case k = 1. Since $\Delta(1, n)$ is an (n-1)-simplex, which does not have any splits, the claim is trivially satisfied. The same holds for k = n - 1 as $\Delta(n - 1, n) \cong \Delta(1, n)$.

For the rest of the proof we assume that $2 \le k \le n-2$. In particular, this implies that $n \ge 4$.

Let $\sum_{i \in [n]} \alpha_i x_i = 0$ define a split hyperplane H of $\Delta(k, n)$. The facet defining hyperplane $F_p = \{x \mid x_p = 0\}$ is intersected by H, and we have

$$F_p \cap H = \left\{ x \in \mathbb{R}^n \mid \sum_{i \in [n] \setminus \{p\}} \alpha_i x_i = 0 = x_p \right\}.$$

Three cases arise:

- (i) $F_p \cap H$ is a facet of $F_p \cap \Delta(k, n) \cong \Delta(k, n 1)$ defined by $x_q = 0$ (with $q \neq p$),
- (ii) $F_p \cap H$ is a facet of $F_p \cap \Delta(k,n) \cong \Delta(k,n-1)$ as defined by Equation (8), or
- (iii) $F_p \cap H$ defines a split of $F_p \cap \Delta(k, n) \cong \Delta(k, n 1)$.

If $F_p \cap H$ is of type (i) then it follows that $\alpha_i = 0$ for all $i \neq p$ and $\alpha_p \neq 0$. As not all the α_i can vanish there is at most one $p \in [n]$ such that $F_p \cap H$ is of type (i). Since we could assume that $n \geq 4$ there are at least two distinct $p, q \in [n]$ such that $F_p \cap H$ and $F_q \cap H$ are of type (ii) or (iii). By symmetry, we can further assume that p = 1 and q = n. So we get a partition (A, B) of [n-1] and a partition (A', B') of $\{2, 3, \ldots, n\}$ with $\mu, \mu' \in \mathbb{N}$ such that $F_1 \cap H$ is defined by $x_1 = 0$ and

$$\mu \sum_{i \in A} x_i = (k - \mu) \sum_{i \in B} x_i \,,$$

while $F_n \cap H$ is defined by $x_n = 0$ and

$$\mu' \sum_{i \in A'} x_i = (k - \mu') \sum_{i \in B'} x_i$$
.

We infer that there is a real number λ such that $\alpha_i = \lambda \mu$ for all $i \in A$, $\alpha_i = \lambda(k - \mu)$ for all $i \in B$. It remains to show that $\alpha_n \in \{\lambda \mu, \lambda(k - \mu)\}$. Similarly, there is a real number λ' such that $\alpha_i = \lambda' \mu'$ for all $i \in A'$, $\alpha_i = \lambda'(k - \mu')$ for all $i \in B'$. As $n \geq 4$ we have $A \cap A' \neq \emptyset$ or $B \cap B' \neq \emptyset$. We obtain $\alpha_i = \lambda \mu = \lambda' \mu'$ for $i \in (A \cap A') \cup (B \cap B')$. Finally, this shows that $\alpha_n \in \{\lambda' \mu', \lambda'(k - \mu')\} = \{\lambda \mu, \lambda(k - \mu)\}$, and this completes the proof.

Theorem 5.3. The total number of splits of the hypersimplex $\Delta(k, n)$ (with $k \leq n/2$) equals

$$(k-1)(2^{n-1}-(n+1))-\sum_{i=2}^{k-1}(k-i)\binom{n}{i}$$
.

Proof. We have to count the $(A,B;\mu)$ -hyperplanes with the restrictions listed in Lemma 5.1. So we take a set $A\subset [n]$ with at least 2 and at most n-2 elements. If A has cardinality i then there are $\min(k-1,n-i-1)-\max(1,k-i+1)+1$ choices for μ . Recall that $(A,B;\mu)$ and $(B,A;k-\mu)$ define the same split; in this way we have counted each split twice. So we get

$$\frac{1}{2} \sum_{i=2}^{n-2} \left(\min(k,n-i) - \max(1,k-i+1) \right) \binom{n}{i} = \frac{1}{2} \sum_{i=2}^{n-2} \left(\min(i,k,n-i) - 1 \right) \binom{n}{i}$$

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splits, where the equality holds since $k \leq n/2$. For a further simplification we rewrite the sum to get

$$\begin{split} \frac{1}{2} \sum_{i=2}^{k-1} (i-1) \binom{n}{i} + \frac{1}{2} \sum_{i=k}^{n-k} (k-1) \binom{n}{i} + \frac{1}{2} \sum_{i=n-k+1}^{n-2} (n-i-1) \binom{n}{i} \\ &= \frac{1}{2} (k-1) \sum_{i=2}^{n-2} \binom{n}{i} + \frac{1}{2} \sum_{i=2}^{k-1} \left(i-1-(k-1) \right) \binom{n}{i} \\ &+ \frac{1}{2} \sum_{i=n-k+1}^{n-2} \left(n-i-1-(k-1) \right) \binom{n}{i} \\ &= (k-1) \left(2^{n-1} - (n+1) \right) - \sum_{i=2}^{k-1} (k-i) \binom{n}{i} \,. \end{split}$$

If we have two distinct splits $(A, B; \mu)$ and $(C, D; \nu)$ then either $\{A \cap C, A \cap D, B \cap C, B \cap D\}$ is a partition of [n] into four parts, or exactly one of the four intersections is empty. If, for instance, $B \cap D = \emptyset$ then $B \subseteq C$ and $D \subseteq A$.

Proposition 5.4. Two splits $(A, B; \mu)$ and $(C, D; \nu)$ of $\Delta(k, n)$ are compatible if and only if one of the following holds:

$$\#(A \cap C) \le k - \mu - \nu$$
, $\#(A \cap D) \le \nu - \mu$,
 $\#(B \cap C) \le \mu - \nu$, or $\#(B \cap D) \le \mu + \nu - k$.

For an arbitrary set $I \subseteq [n]$ we abbreviate $x_I := \sum_{i \in I} x_i$. In particular, $x_{\varnothing} = 0$ and for $x \in \Delta(k, n)$ one has $x_{[n]} = k$.

Proof. Let $x \in \Delta(k, n)$ be in the intersection of the $(A, B; \mu)$ -hyperplane and the $(C, D; \nu)$ -hyperplane. Our split equations take the form

$$\mu(x_{A\cap C} + x_{A\cap D}) = (k - \mu)(x_{B\cap C} + x_{B\cap D}) \quad \text{and}$$
$$\nu(x_{A\cap C} + x_{B\cap C}) = (k - \nu)(x_{A\cap D} + x_{B\cap D}).$$

In view of $(A \cap C) \cup (A \cap D) \cup (B \cap C) \cup (B \cap D) = [n]$ we additionally have $x_{A \cap C} + x_{A \cap D} + x_{B \cap C} + x_{B \cap D} = k$, and thus we arrive at the equivalent system of linear equations

$$x_{A \cap C} = k - \mu - \nu + x_{B \cap D}$$
, $x_{A \cap D} = \nu - x_{B \cap D}$, and $x_{B \cap C} = \mu - x_{B \cap D}$

from which we can further derive

(11)
$$x_A = k - \mu$$
, $x_B = \mu$, $x_C = k - \nu$, and $x_D = \nu$.

Now the two given splits are *incompatible* if and only if there exists a point $x \in (0,1)^n$ satisfying the conditions (10).

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Suppose first that none of the four intersections $A \cap C$, $A \cap D$, $B \cap C$, and $B \cap D$ is empty. Then $x \in (0,1)^n$ satisfies the Equations (10) if and only if the system of inequalities in $x_{B \cap D}$

has a solution. This is equivalent to the following system of inequalities:

$$\begin{array}{ll} 0 & < x_{B\cap D} < \#(B\cap D) \\ \mu + \nu - k & < x_{B\cap D} < \#(A\cap C) + \mu + \nu - k \\ \mu - \#(B\cap C) < x_{B\cap D} < \mu \\ \nu - \#(A\cap D) < x_{B\cap D} < \nu \,. \end{array}$$

Obviously, the latter system admits a solution if and only if each of the four terms on the left is smaller than each of the four terms on the right. Most of the resulting 16 inequalities are redundant. The following four inequalities remain

$$\#(A \cap C) > k - \mu - \nu$$

 $\#(A \cap D) > \nu - \mu$
 $\#(B \cap C) > \mu - \nu$
 $\#(B \cap D) > \mu + \nu - k$,

and this completes the proof of this case.

For the remaining cases, we can assume by symmetry that $A \cap C = \emptyset$. Then $x \in (0,1)^n$ satisfies the Equations (10) if and only if $x_{B \cap D} = \mu + \nu - k$, $x_{A \cap D} = k - \mu$, and $x_{B \cap C} = k - \nu$. So the splits are not compatible if and only if

$$\begin{array}{ll} 0 < k - \mu & <\#(A \cap D) = \#A \\ 0 < k - \nu & <\#(B \cap C) = \#C \\ 0 < \mu + \nu - k < \#(B \cap D) \,. \end{array}$$

Since, by Lemma 5.1, the first two inequalities hold for all splits this proves that the splits are compatible if and only if

$$\#(A \cap C) = 0 \le k - \mu - \nu$$
 or $\#(B \cap D) \le \mu + \nu - k$.

However, again by using Lemma 5.1, one has $\#(A \cap D) = \#A > k - \mu > \nu - \mu$, so $\#(A \cap D) \leq \nu - \mu$ and, similarly, $\#(B \cap C) \leq \mu - \nu$ cannot be true. This completes the proof.

In fact, the four cases of the proposition are equivalent in the sense that, by renaming the four sets and exchanging μ and ν or μ and $k-\mu$ in a suitable way, one will always be in the first case.

Example 5.5. We consider the case k = 3 and n = 6. For instance, the splits $(\{1, 2, 6\}, \{3, 4, 5\}; 2)$ and $(\{4, 5, 6\}, \{1, 2, 3\}; 2)$ are compatible since the

intersection $\{3,4,5\} \cap \{1,2,3\} = \{3\}$ has only one element and 2+2-3=1, that is, the inequality " $\#(C \cap D) \le \mu + \nu - k$ " is satisfied.

Corollary 5.6. Two splits $(A, B; \mu)$ and $(A, B; \nu)$ of $\Delta(k, n)$ are always compatible.

Proof. Without loss of generality we can assume that $\mu \geq \nu$. Then the condition "# $(B \cap C) \leq \mu - \nu$ " of Proposition 5.4 is satisfied.

In Proposition 7.6 below we will show that the 1-skeleton of the weak split complex of any hypersimplex is always a complete graph. In particular, the weak split complex of $\Delta(k, n)$ is connected. (Or it is void if $k \in \{1, n-1\}$.)

6. Finite Metric Spaces

This section revisits the classical case, studied in the papers by Bandelt and Dress [1, 2]; see also Isbell [20]. Its purpose is to show how some of the key results can be obtained as immediate corollaries to our results above.

Let $\delta: \binom{[n]}{2} \to \mathbb{R}_{\geq 0}$ be a metric on the finite set [n]; that is, δ is a symmetric dissimilarity function which obeys the triangle inequality. By setting

$$w_{\delta}(e_i + e_j) := -\delta(i, j)$$

each metric δ defines a weight function w_{δ} on the second hypersimplex $\Delta(2, n)$. Hence the results for k = 2 from Section 5 can be applied here. The *tight span* of δ is the tight span $\mathfrak{T}_{w_{\delta}}(\Delta(2, n))$.

Let S = (A, B) be a *split partition* of the set [n], that is, $A, B \subseteq [n]$ with $A \cup B = [n]$, $A \cap B = \emptyset$, $\#A \ge 2$, and $\#B \ge 2$. This gives rise to the *split metric*

$$\delta_S(i,j) := \begin{cases} 0 & \text{if } \{i,j\} \subseteq A \text{ or } \{i,j\} \subseteq B, \\ 1 & \text{otherwise.} \end{cases}$$

The weight function $w_{\delta_S} = -\delta_S$ induces a split of the second hypersimplex $\Delta(2, n)$, which is induced by the (A, B; 1)-hyperplane defined in Equation (9). Proposition 5.2 now implies the following characterization.

Corollary 6.1. Each split of $\Delta(2,n)$ is induced by a split metric.

Specializing the formula in Theorem 5.3 with k=2 gives the following.

Corollary 6.2. The total number of splits of the hypersimplex $\Delta(2,n)$ equals $2^{n-1} - n - 1$.

The following corollary and proposition shows that our notions of compatibility and weak compatibility agree with those of Bandelt and Dress [2] for in the special case of $\Delta(2, n)$.

Corollary 6.3 (Hirai [17], Proposition 4.16). Two splits (A, B) and (C, D) of $\Delta(2, n)$ are compatible if and only if one of the four sets $A \cap C$, $A \cap D$, $B \cap C$, and $B \cap D$ is empty.

Proof. Let (A, B) and (C, D) be splits of $\Delta(2, n)$. We are in the situation of Proposition 5.4 with k = 2 and $\mu = \nu = 1$. Hence all the right hand sides of the four inequalities in Proposition 5.4 yield zero, and this gives the claim. \square

For a splits S = (A, B) of $\Delta(2, n)$ and $m \in [n]$ we denote by S(m) that of the two set A, B with $m \in S(m)$.

Proposition 6.4. A set S of splits of $\Delta(2,n)$ is weakly compatible if and only if there does not exist $m_0, m_1, m_2, m_3 \in [n]$ and $S_1, S_2, S_3 \in S$ such that $m_i \in S_j$ if and only if i = j.

Proof. This is the definition of a weakly compatible split system $\Delta(2, n)$ originally given by Bandelt and Dress in [2, Section 1, page 52]. Their Corollary 10 states that S is weakly compatible in their sense if and only if $\sum_{S \in S} w_S$ is a coherent decomposition. However, this is our definition of weakly compatibility according to Lemma 3.12.

Example 6.5. The hypersimplex $\Delta(2,4)$ is the regular octahedron, already studied in Example 4.9. It has the three splits $(\{1,2\},\{3,4\})$, $(\{1,3\},\{2,4\})$, and $(\{1,4\},\{2,3\})$. The weak split complex is a triangle, and the split compatibility graph consists of three isolated points.

The split compatibility graph of $\Delta(2,5)$ is isomorphic to the Petersen graph. It is shown in Figure 5.

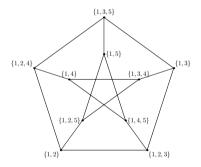


FIGURE 5. Split compatibility graph of $\Delta(2,5)$; a split (A,B) with $1 \in A$ is labeled "A".

By Proposition 4.6 each compatible system of splits gives rise to a tree. On the other hand, given a tree with n labeled leaves take for each edge E that is not connected to a leave the split (A, B) where A is the set of labels on one side of E and B the set of labels on the other side. So each tree gives rise to a system of splits for $\Delta(2, k)$ which is easily seen to be compatible. This argument can be augmented to a proof of the following theorem.

Theorem 6.6 (Buneman [6]; Billera, Holmes, and Vogtmann [3]). The split complex $Split(\Delta(2, n))$ is the complex of trivalent leaf-labeled trees with n leaves.

The split complex Split($\Delta(2, n)$) is equal to the link of the origin L_{n-1} of the space of phylogenetic trees in [3]. It was proved in [42, Theorem 2.4] (see also Robinson and Whitehouse [35]) that Split($\Delta(2, n)$) is homotopy equivalent to a wedge of n-3 spheres. By a result of Trappmann and Ziegler, Split($\Delta(2, n)$) is even shellable [41]. Markwig and Yu [31] recently identified the space of k tropically collinear points in the tropical (d-1)-dimensional affine space as a (shellable) subcomplex of Split($\Delta(2, k+d)$).

Example 6.7. Consider the split system $S = \{(A_{ij}, [n] \setminus A_{ij}) | 1 \le i < j \le n \text{ and } j-i < n-2\}$ where $A_{ij} := \{i, i+1, \ldots, j-1, j\}$ for the hypersimplex $\Delta(2, n)$. The combinatorial criterion of Proposition 6.4 shows that this split system is weakly compatible, and that $\#S = \binom{n}{2} - n$. Since $\Delta(2, n)$ has $\binom{n}{2}$ vertices and is of dimension n-1, Corollary 4.5 implies that $\Sigma_S(P)$ is a triangulation. This triangulation is known as the thrackle triangulation in the literature; see [8], [40, Chapter 14], and additionally [39, 2, 29, 15] for further occurrences of this triangulation. In fact, as one can conclude from [11, Theorem 3.1] in connection with [2, Theorem 5], this is the only split triangulation of $\Delta(2, n)$, up to symmetry.

7. Matroid Polytopes and Tropical Grassmannians

In the following, we copy some information from Speyer and Sturmfels [38]; the reader is referred to this source for the details.

Let $\mathbb{Z}[p] := \mathbb{Z}[p_{i_1,\dots,i_k} \mid 1 \leq i_1 < i_2 < \dots < i_k \leq n]$ be the polynomial ring in $\binom{n}{k}$ indeterminates with integer coefficients. The indeterminate p_{i_1,\dots,i_k} can be identified with the $k \times k$ -minor of a $k \times n$ -matrix with columns numbered (i_1,i_2,\dots,i_k) . The *Plücker ideal* $I_{k,n}$ is defined as the ideal generated by the algebraic relations among these minors. It is obviously homogeneous, and it is known to be a prime ideal. For an algebraically closed field K the projective variety defined by $I_{k,n} \otimes_{\mathbb{Z}} K$ in the polynomial ring $K[p] = \mathbb{Z}[p] \otimes_{\mathbb{Z}} K$ is the *Grassmannian* $G_{k,n}$ (over K). It parameterizes the k-dimensional linear subspaces of the vector space K^n .

For instance, we can pick K as the algebraic closure of the field $\mathbb{C}(t)$ of rational functions. Then for an arbitrary ideal I in $K[x] = K[x_1, \ldots, x_m]$ its $tropicalization \ \mathcal{T}(I)$ is the set of all vectors $w \in \mathbb{R}^m$ such that the initial ideal $in_w(I)$ with respect to the term order defined by the weight function w does not contain any monomial. The $tropical\ Grassmannian\ \mathfrak{G}_{k,n}$ (over K) is the tropicalization of the Plücker ideal $I_{k,n} \otimes_{\mathbb{Z}} K$.

The tropical Grassmannian $\mathcal{G}_{k,n}$ is a polyhedral fan in $\mathbb{R}^{\binom{n}{k}}$ such that each of its maximal cones has dimension (n-k)k+1. In a way the fan $\mathcal{G}_{k,n}$ contains redundant information. We describe the three step reduction in [38, Section 3].

Let ϕ be the linear map from \mathbb{R}^n to $\mathbb{R}^{\binom{n}{k}}$ which sends $x = (x_1, \ldots, x_n)$ to $(x_I | I \in \binom{n}{k})$. Recall that x_I is defined as $\sum_{i \in I} x_i$. The map ϕ is injective, and its image im ϕ coincides with the intersection of all maximal cones in $\mathcal{G}_{k,n}$. Moreover, the vector $\mathbb{I} := (1, 1, \ldots, 1)$ of length $\binom{n}{k}$ is contained in the image

of ϕ . This leads to the definition of the two quotient fans

$$\mathfrak{G}'_{k,n}:=\mathfrak{G}_{k,n}/\mathbb{R}\mathbb{1}$$
 and $\mathfrak{G}''_{k,n}:=\mathfrak{G}_{k,n}/\operatorname{im}\phi$.

Finally, let $\mathcal{G}_{k,n}^{"'}$ be the (spherical) polytopal complex arising from intersecting $\mathcal{G}_{k,n}^{"}$ with the unit sphere in $\mathbb{R}^{\binom{n}{k}}/\operatorname{im}\phi$. We have $\dim \mathcal{G}_{k,n}^{"'}=n(k-1)-k^2$. It seems to be common practice to use the name "tropical Grassmannian" interchangeably for $\mathcal{G}_{k,n}$, $\mathcal{G}_{k,n}^{'}$, $\mathcal{G}_{k,n}^{"}$, as well as $\mathcal{G}_{k,n}^{"'}$.

It is unlikely that it is possible to give a complete combinatorial description of all tropical Grassmannians. The contribution of combinatorics here is to provide kind of an "approximation" to the tropical Grassmannians via matroid theory. For a background on matroids, see the books edited by White [43, 44].

The tropical pre-Grassmannian pre- $\mathcal{G}_{k,n}$ is the subfan of the secondary fan of $\Delta(k,n)$ of those weight functions which induce matroid subdivisions. A polytopal subdivision Σ of $\Delta(k,n)$ is a matroid subdivision if each (maximal) cell is a matroid polytope. If M is a matroid on the set [n] then the corresponding matroid polytope is the convex hull of those 0/1-vectors in \mathbb{R}^n which are characteristic functions of the bases of M. A finite point set $X \subset \mathbb{R}^d$ (possibly with multiple points) gives rise to a matroid $\mathfrak{M}(X)$ by taking as bases for $\mathfrak{M}(X)$ the maximal affinely independent subsets of X. The following characterization of matroid subdivisions is essential.

Theorem 7.1 (Gel'fand, Goresky, MacPherson, and Serganova [13], Theorem 4.1). Let Σ be a polytopal subdivision of $\Delta(k, n)$. The following are equivalent:

- (i) The maximal cells of Σ are matroid polytopes, that is, Σ is a matroid subdivision.
- (ii) the 1-skeleton of Σ coincides with the 1-skeleton of $\Delta(k,n)$, and
- (iii) the edges in Σ are parallel to the edges of $\Delta(k, n)$.

Regular matroid subdivisions of hypersimplices are called "generalized Lie complexes" by Kapranov [24]. The corresponding equivalence classes of weight functions are the "tropical Plücker vectors" of Speyer [36].

The relationship between the two fans $\operatorname{pre}-\mathcal{G}_{k,n}$ and $\mathcal{G}_{k,n}$ is the following. Algebraically, $\operatorname{pre}-\mathcal{G}_{k,n}$ is the tropicalization of the ideal of quadratic Plücker relations; see Speyer [36, Section 2]. Conversely, each weight function in the fan $\mathcal{G}_{k,n}$ gives rise to a matroid subdivision of $\Delta(k,n)$. However, since there is no secondary fan naturally associated with $\mathcal{G}_{k,n}$ it is a priori not clear how $\mathcal{G}_{k,n}$ sits inside $\operatorname{pre}-\mathcal{G}_{k,n}$. Note that, unlike $\mathcal{G}_{k,n}$, the tropical pre-Grassmannian does not depend on the characteristic of the field K.

Our goal for the rest of this section is to explain how the hypersimplex splits are related to the tropical (pre-)Grassmannians.

Proposition 7.2. Let Σ be a matroid subdivision and S a split of $\Delta(k, n)$. Then Σ and S have a common refinement (without new vertices).

Proof. Of course, one can form the common refinement Σ' of Σ and S but Σ' may contain additional vertices, and hence does not have to be a polytopal

subdivision of $\Delta(k, n)$. However, additional vertices can only occur if some edge of Σ is cut by the hyperplane H_S . By Theorem 7.1, all edges of Σ are edges of $\Delta(k, n)$. But since S is a split, it does not cut any edges of $\Delta(k, n)$. Therefore Σ' is a common refinement of S and Σ without new vertices.

In order to continue, we recall some notions from linear algebra: Let V be vector space. A set $A \subset V$ is said to be in *general position* if any subset S of B with $\#S \leq \dim V + 1$ is affinely independent. A family $\mathcal{A} = \{A_i \mid i \in I\}$ in V is said to be in *relative general position* if for each affinely dependent set $S \subseteq \bigcup_{i \in I} A_i$ with $\#S \leq \dim V + 1$ there exists some $i \in I$ such that $S \cap A_i$ is affinely dependent.

Lemma 7.3. Let M be a matroid of rank k defined by $X \subset \mathbb{R}^{k-1}$. If there exists some family $A = \{A_i | i \in I\}$ of sets in general position with respect to $X := \bigcup_{i \in I} A_i$ such that each A_i is in general position as a subset of aff A_i then the set of bases of M is given by

$$(13) \{B \subset X \mid \#B = k \text{ and } \#(B \cap A_i) \leq \dim \operatorname{aff} A_i + 1 \text{ for all } i \in I\} .$$

Proof. It is obvious that for each basis B of \mathfrak{M} one has $\#(B \cap A_i) \leq \dim \operatorname{aff} A_i + 1$ for all $i \in I$. So it remains to show that each set B in (13) is affinely independent. Let B be such a set and suppose that B is not affinely independent. Since A is in relative general position there exists some $i \in I$ such that $B \cap A_i$ is affinely dependent. However, since $\#(B \cap A_i) \leq \dim \operatorname{aff} A_i + 1$, this contradicts the fact that A_i is in general position in aff A_i .

From each split $(A, B; \mu)$ of $\Delta(k, n)$ we construct two matroid polytopes with points labeled by [n]: Take any $(\mu - 1)$ -dimensional (affine) subspace $U \subset \mathbb{R}^{k-1}$ and put #B points labeled by B into U such that they are in general position (as a subset of U). The remaining points, labeled by A, are placed in $\mathbb{R}^{k-1} \setminus U$ such that they are in general position and in relative general position with respect to the set of points labeled by B. By Lemma 7.3 the bases of the corresponding matroid are all k-element subsets of [n] with at most μ points in B. These are exactly the points in one side of (9). The second matroid is obtained symmetrically, that is, starting with #A points in a $(k - \mu - 1)$ -dimensional subspace. Since splits are regular and correspond to rays in the secondary fan we have proved the following lemma.

Lemma 7.4. Each split of $\Delta(k,n)$ defines a regular matroid subdivision and hence a ray in pre- $\mathcal{G}_{k,n}$.

Matroids arising in this way are called *split matroids*, and the corresponding matroid polytopes are the *split matroid polytopes*.

Remark 7.5. Kim [25] studies the splits of general matroid polytopes. However, his definition of a split requires that it induces a matroid subdivision. Lemma 7.4 shows that for the entire hypersimplex these notions agree. In this case, [25, Theorem 4.1] reduces to our Lemma 5.1.

Proposition 7.6. The 1-skeleton of the weak split complex $Split^{w}(\Delta(k, n))$ of $\Delta(k, n)$ is a complete graph.

Proof. We have to prove that any two splits of $\Delta(k, n)$ are weakly compatible. Since splits are matroid subdivisions by Lemma 7.4 this immediately follows from Proposition 7.2.

Example 7.7. We continue our Example 6.5, where k=2 and n=4. Up to symmetry, each split of the regular octahedron $\Delta(2,4)$ looks like ($\{1,2\}$, $\{3,4\}$; 1), that is, $\mu=1$.

In this case, the affine subspace U is just a single point on the line \mathbb{R}^1 . The only choice for the two points corresponding to $B=\{3,4\}$ is the point U itself. The two points corresponding to $A=\{1,2\}$ are two arbitrary distinct points both of which are distinct from U. The situation is displayed in Figure 6 on the left. This defines the first of the two matroids induced by the split $(\{1,2\},\{3,4\};1)$. Its bases are $\{1,2\},\{1,3\},\{1,4\},\{2,3\},$ and $\{2,4\}$.

The second matroid is obtained in a similar way. Both matroid polytopes are square pyramids, and they are shown (with their vertices labeled) in Figure 6 on the right. The pyramid in bold is the one corresponding to the matroid whose construction has been explained in detail above and which is shown on the left.

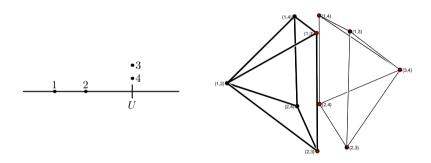


FIGURE 6. Matroid and matroid subdivision induced by a split as explained in Example 7.7.

As in the case of the tropical Grassmannian, we can intersect the fan $\operatorname{pre-}\mathcal{G}_{k,n}$ with the unit sphere in $\mathbb{R}^{\binom{n}{k}-n}$ to arrive at a (spherical) polytopal complex $\operatorname{pre-}\mathcal{G}'_{k,n}$, which we also call the *tropical pre-Grassmannian*. The following is one of our main results.

Theorem 7.8. The split complex $Split(\Delta(k,n))$ is a polytopal subcomplex of the tropical pre-Grassmannian $pre-\mathcal{G}'_{k,n}$.

Proof. By Proposition 4.2, the split complex is a subcomplex of SecFan' $(\Delta(k, n))$. Furthermore, by Lemma 7.4 each split corresponds to a

ray of pre- $\mathcal{G}_{k,n}$. So it remains to show that all maximal cells of $\Sigma_{\mathcal{S}}(\Delta(k,n))$ are matroid polytopes whenever \mathcal{S} is a compatible system of splits. The proof will proceed by induction on k and n. Note that, since $\Delta(k,n) \cong \Delta(n-k,n)$, it is enough to have as base case k=2 and arbitrary n, which is given by Proposition 7.11.

By Theorem 7.1, we have to show that there do not occur any edges in $\Sigma_{\mathbb{S}}(\Delta(k,n))$ that are not edges of $\Delta(k,n)$. Since \mathbb{S} is compatible no split hyperplanes meet in the interior of $\Delta(k,n)$, and so additional edges could only occur in the boundary. By Observation 3.1, for each split $S \in \mathbb{S}$ and each facet F of $\Delta(k,n)$ there are two possibilities: Either H_S does not meet the interior of F, or H_S induces a split S' on F. The restriction of $\Sigma_{\mathbb{S}}(\Delta(k,n))$ to F equals the common refinement of all such splits S'. So, using the induction hypothesis and again Theorem 7.1, it suffices to prove that the split systems that arise in this fashion are compatible.

So let $S = (A, B, \mu) \in \mathcal{S}$. We have to consider to types of facets of $\Delta(k, n)$ induced by $x_i = 0$, $x_i = 1$, respectively. In the first case, the arising facet F is isomorphic to $\Delta(k, n - 1)$ and, if H_S meets F in the interior, the split S' of F equals $(A \setminus \{i\}, B; \mu)$ or $(A, B \setminus \{i\}; \mu)$. It is now obvious by Proposition 5.4 that the system of all such S' is compatible if S was.

In the second case, the facet F is isomorphic to $\Delta(k-1,n-1)$ and S' (again if H_S meets the interior of F at all) equals $(A\setminus\{i\},B;\mu)$ or $(A,B\setminus\{i\};\mu-1)$. To show that a split system is compatible it suffices to show that any two of its splits are compatible. So let $S=(A,B;\mu)$ and $T=(C,D;\nu)$ be compatible splits for $\Delta(k,n)$ such that H_S and H_T meet the interior of F, and $S'=(A',B';\mu')$, $T'=(C',D';\nu')$, respectively, the corresponding splits of F. By the remark after Proposition 5.4, we can suppose that we are in the first case of Proposition 5.4, that is, $\#(A\cap C) \leq k-\mu-\nu$. We now have to consider the four cases that i is an element of either $A\cap C$, $A\cap D$, $B\cap C$, or $B\cap D$. In the first case, we have $S'=(A\setminus\{i\},B;\mu)$ and $T'=(C\setminus\{i\},D,\nu)$. We get $\#(A'\cap C')=\#(A\cap B)-1\leq k-\mu-\nu-1=(k-1)-\mu'-\nu'$, so S' and T' are compatible. The other cases follow similarly, and this completes the proof of the theorem.

Construction 7.9. We will now explicitly construct the matroid polytopes that occur in the refinement of two compatible splits. So consider two compatible splits of $\Delta(k,n)$ defined by an $(A,B;\mu)$ - and a $(C,D;\nu)$ -hyperplane. These two hyperplanes divide the space into four (closed) regions. Compatibility implies that the intersection of one of these regions with $\Delta(k,n)$ is not full-dimensional, two of the intersections are split matroid polytopes, and the last one is a full-dimensional polytope of which we have to show that it is a matroid polytope. It therefore suffices to show that one of the four intersections is a full-dimensional matroid polytope that is not a split matroid polytope.

By Proposition 5.4 and the remark following its proof, we can assume without loss of generality that $\#(B \cap D) \leq \mu + \nu - k$. Note first that the equation $\sum_{i \in B} x_i = \mu$ also defines the $(A, B; \mu)$ -hyperplane from Equation (9), since

 $x_{A \cup B} = k$ for any point $x \in \Delta(k, n)$. We will show that the intersection of $\Delta(k, n)$ with the two halfspaces defined by

$$\sum_{i \in B} x_i \le \mu \quad \text{and} \quad \sum_{i \in D} x_i \le \nu$$

is a full dimensional matroid polytope which is not a split matroid polytope.

To this end, we define a matroid on the ground set [n] together with a realization in \mathbb{R}^{k-1} as follows. Pick a pair of (affine) subspaces U_B and U_D of \mathbb{R}^{k-1} such that the following holds: $\dim U_B = \mu - 1$, $\dim U_D = \nu - 1$, and $\dim(U_B \cap U_D) = \mu + \nu - k - 1$. Note that the latter expression is non-negative as $0 \le \#(B \cap D) \le \mu + \nu - k - 1$. The dimension formula then implies that $\dim(U_B + U_D) = \mu - 1 + \nu - 1 - \mu - \nu + k + 1 = k - 1$, that is, $U_B + U_D = \mathbb{R}^{k-1}$.

Each element in [n] labels a point in \mathbb{R}^{k-1} according to the following restrictions. For each element in the intersection $B \cap D$ we pick a point in $U_B \cap U_D$ such that the points with labels in $B \cap D$ are in general position within $U_B \cap U_D$. Since $\#(B \cap D) \leq \mu + \nu - k$ the points with labels in $B \cap D$ are also in general position within U_B . Therefore, for each element in $B \setminus D = B \cap C$ we can pick a point in $U_B \setminus (U_B \cap U_D)$ such that all the points with labels in B are in general position within U_B . Similarly, we can pick points for the elements of $D \cap A$ in $U_D \setminus (U_B \cap U_D)$ such that the points with labels in D are in general position within U_D . Without loss of generality, we can assume that the points with labels in D and the points with labels in D are in relative general position as subsets of $U_B + U_D = \mathbb{R}^{k-1}$.

For the remaining elements in $A \cap C = [n] \setminus (B \cup D)$ we can pick points in $\mathbb{R}^{k-1} \setminus (U_B \cup U_D)$ such that the points with labels in $A \cap C$ are in general position and the family of sets of points with labels in B, D, and $A \cap C$, respectively, is in relative general position. By Lemma 7.3 the matroid generated by this point set has the desired property.

Example 7.10. We continue our Example 5.5, where k=3 and n=6, considering the compatible splits $(\{1,2,6\},\{3,4,5\};2)$ and $(\{4,5,6\},\{1,2,3\};2)$. In the notation used in Construction 7.9 we have $A=\{1,2,6\}$, $B=\{3,4,5\}$, $C=\{4,5,6\}$, $D=\{1,2,3\}$, and $\mu=\nu=2$. Hence $A\cap C=\{6\}$, $A\cap D=\{1,2\}$, $B\cap C=\{4,5\}$, and $B\cap D=\{3\}$. The matroid from Construction 7.9 is displayed in Figure 7. The non-split matroid polytope constructed in the proof of Theorem 7.8 has the f-vector (18,72,101,59,14).

For the special case k=2 the structure of the tropical Grassmannian and pre-Grassmannian is much simpler. The following proposition follows from [38, Theorem 3.4], in connection with Theorem 6.6.

Proposition 7.11. The tropical Grassmannian $\mathfrak{G}_{2,n}^{"'}$ equals $\operatorname{pre-}\mathfrak{G}_{2,n}^{'}$, and it is a simplicial complex which is isomorphic to the split complex $\operatorname{Split}(\Delta(2,n))$.

Let us revisit the two smallest cases: The tropical Grassmannian $\mathcal{G}_{2,4}^{\prime\prime\prime}$ consists of three isolated points corresponding to the three splits of the regular octahedron, and $\mathcal{G}_{2,5}^{\prime\prime\prime}$ is a 1-dimensional simplicial complex isomorphic to the Petersen graph; see Figure 5.

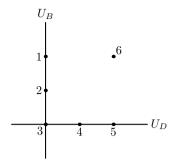


FIGURE 7. Non-split matroid constructed from two compatible splits in $\Delta(3,6)$ as in Example 7.10.

Proposition 7.12. The rays in pre- $\mathcal{G}_{k,n}$ correspond to the coarsest regular matroid subdivisions of $\Delta(k,n)$.

Proof. By definition, a ray in pre- $\mathcal{G}_{k,n}$ defines a regular matroid subdivision which is coarsest among the matroid subdivisions of $\Delta(k,n)$. We have to show that this is a coarsest among all subdivisions.

To the contrary, suppose that Σ is a coarsest matroid subdivision which can be coarsened to a subdivision Σ' . By construction the 1-skeleton of Σ' is contained in the 1-skeleton of Σ . From Theorem 7.1 it follows that Σ' is matroidal. This is a contradiction to Σ being a coarsest matroid subdivision.

Example 7.13. In view of Proposition 7.11, the first example of a tropical Grassmannian that is not covered by the previous results is the case k = 3 and n = 6. So we want to describe how the split complex $Split(\Delta(3,6))$ is embedded into $G_{3,6}^{""}$. We use the notation of [38, Section 5]; see also [37, Section 4.3].

The tropical Grassmannian $\mathcal{G}_{3,6}^{\prime\prime\prime}$ is a pure 3-dimensional simplicial complex which is not a flag complex. Its f-vector reads (65,550,1395,1035), and its homology is concentrated in the top dimension. The only non-trivial (reduced) homology group (with integral coefficients) is $H_3(\mathcal{G}_{3,6}^{\prime\prime\prime};\mathbb{Z}) = \mathbb{Z}^{126}$.

The splits with $A = \{1\} \cup A_1$, $\mu = 1$, and $A = \{1\} \cup A_3$, $\mu = 2$, are the 15 vertices of type "F". The splits with $A = \{1\} \cup A_2$ and $\mu \in \{1,2\}$ are the 20 vertices of type "E". Here A_m is an m-element subset of $\{2,3,\ldots,n\}$. The remaining 30 vertices are of type "G", and they correspond to coarsest subdivisions of $\Delta(3,6)$ into three maximal cells. Hence they do not occur in the split complex. See also Billera, Jia, and Reiner [4, Example 7.13].

The 100 edges of type "EE" and the 120 edges of type "EF" are the ones induced by compatibility. Since $\mathrm{Split}(\Delta(3,6))$ does not contain any "FF"-edges it is not an induced subcomplex of $\mathcal{G}_{3,6}'''$. The matroid shown in Figure 7 arises from an "EE"-edge.

The split complex is 3-dimensional and not pure; it has the f-vector (35, 220, 360, 30). The 30 facets of dimension 3 are the tetrahedra of type "EEEE". The remaining 240 facets are "EEF"-triangles.

The integral homology of $Split(\Delta(3,6))$ is concentrated in dimension two, and it is free of degree 144.

Remark 7.14. Example 7.13 and Proposition 7.11 show that the split complex is a subcomplex of $\mathcal{G}_{k,n}^{\prime\prime\prime}$ if d=2 or $n\leq 6$. However, this does not hold in general: Consider the weight functions w,w' defined in the proof of [38, Theorem 7.1]. It is easily seen from Proposition 5.4 that w and w' are the sum of the weight functions of compatible systems of vertex splits for $\Delta(3,7)$. Yet in the proof of [38, Theorem 7.1], it is shown that $w,w'\notin\mathcal{G}_{3,7}^{\prime\prime\prime}$ for fields with characteristic not equal to 2 and equal to 2, respectively.

8. Open Questions and Concluding Remarks

We showed that special split complexes of polytopes (e.g., of the polygons and of the second hypersimplices) already occurred in the literature albeit not under this name. So the following is natural to ask.

Question 8.1. What other known simplicial complexes arise as split complexes of polytopes?

The split hyperplanes of a polytope define an affine hyperplane arrangement. For example, the coordinate hyperplane arrangements arises as the split hyperplane arrangement of the cross polytopes; see Example 4.9.

Question 8.2. Which hyperplane arrangements arise as split hyperplane arrangements of some polytope?

Jonsson [21] studies generalized triangulations of polygons; this has a natural generalization to simplicial complexes of split systems such that no k + 1 splits in such a system are totally incompatible. See also [33, 10].

Question 8.3. How do such *incompatibility complexes* look alike for other polytopes?

All computations with polytopes, matroids, and simplicial complexes were done with polymake [12]. The visualization also used JavaView [34].

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